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AEROoffice V5.6.0 2018-03-06  
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Dongle-ID: 3-3541217

Boresight Misalignment Calculations  
28/07/2020 16:50:17

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Project: 0014\_240720  
Projectfile: C:\AEROofficeV51\PROYECTOS\07\_PROYECTOS\_EAGLE80\

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Used input data:

Platform Solution: C:\AEROofficeV51\PROYECTOS\07\_PROYECTOS\_EAGLE80\Pol-Cal.aps  
Event Mark File : C:\AEROofficeV51\PROYECTOS\07\_PROYECTOS\_EAGLE80\Pol-Cal.aom  
AT Result File : C:\AEROofficeV51\PROYECTOS\07\_PROYECTOS\_EAGLE80\EQ\_xyzopk.txt  
Importformat File: C:\AEROofficeV51\FORMATOS\PTOFORMAT

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Coordinate system scalefactor correction for height applied  
Using DTM

Local Coordinate System:  
UTM - ETRS89 SPH - ellipsoidal Altitude  
System defined in: built-in coordinate system  
Selected Zone: 30N  
Meridian Convergence corrected

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Loading INS Data  
328 usable events found

Loading AT Data  
AT input: angles found  
53 AT Data Sets imported  
53 events with matching eventnumbers found.

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Postion offset for the single events [m]:

	number	time	east	north	alt	d east	d north	d alt
position:	1789	470968.30	-0.013	0.006	-0.088	-0.013	0.006	-0.088
position:	1790	470982.99	-0.061	0.041	-0.055	-0.061	0.041	-0.055
position:	1791	470997.80	-0.091	-0.031	-0.050	-0.091	-0.031	-0.050
position:	1792	471012.55	-0.113	0.024	0.015	-0.113	0.024	0.015
position:	1793	471027.59	-0.099	0.015	0.008	-0.099	0.015	0.008
position:	1794	471042.88	-0.127	0.042	0.030	-0.127	0.042	0.030
position:	1795	471058.28	-0.103	-0.001	0.017	-0.103	-0.001	0.017
position:	1796	471073.79	-0.044	-0.005	0.003	-0.044	-0.005	0.003
position:	1797	471089.19	-0.100	0.035	0.009	-0.100	0.035	0.009
position:	1798	471104.97	-0.103	0.011	0.027	-0.103	0.011	0.027
position:	1799	471120.38	-0.009	-0.003	-0.025	-0.009	-0.003	-0.025
position:	1800	471135.37	-0.065	0.053	0.027	-0.065	0.053	0.027
position:	1801	471150.59	-0.042	0.036	0.050	-0.042	0.036	0.050
position:	1772	470587.58	0.083	0.031	-0.195	0.083	0.031	-0.195
position:	1773	470600.19	0.151	0.033	-0.128	0.151	0.033	-0.128
position:	1774	470612.77	0.187	-0.005	-0.091	0.187	-0.005	-0.091
position:	1775	470625.59	0.203	0.028	-0.052	0.203	0.028	-0.052
position:	1776	470638.16	0.144	0.032	-0.101	0.144	0.032	-0.101
position:	1777	470650.88	0.160	0.004	-0.084	0.160	0.004	-0.084
position:	1778	470663.17	0.189	-0.008	-0.110	0.189	-0.008	-0.110
position:	1779	470675.07	0.103	0.005	-0.158	0.103	0.005	-0.158
position:	1780	470687.17	0.162	-0.012	-0.087	0.162	-0.012	-0.087
position:	1781	470699.16	0.158	0.016	-0.154	0.158	0.016	-0.154
position:	1782	470711.36	0.149	-0.046	-0.141	0.149	-0.046	-0.141
position:	1783	470723.55	0.074	-0.063	-0.095	0.074	-0.063	-0.095
position:	1784	470735.66	0.053	0.008	-0.048	0.053	0.008	-0.048
position:	1613	468207.07	-0.076	-0.070	-0.013	-0.076	-0.070	-0.013
position:	1614	468221.97	-0.168	-0.052	0.067	-0.168	-0.052	0.067
position:	1615	468236.98	-0.168	-0.054	0.064	-0.168	-0.054	0.064
position:	1616	468251.87	-0.184	-0.003	0.076	-0.184	-0.003	0.076
position:	1617	468266.78	-0.154	-0.003	0.100	-0.154	-0.003	0.100
position:	1618	468281.77	-0.194	-0.030	0.111	-0.194	-0.030	0.111
position:	1619	468296.96	-0.170	-0.027	0.128	-0.170	-0.027	0.128
position:	1620	468311.95	-0.199	-0.030	0.152	-0.199	-0.030	0.152
position:	1621	468326.85	-0.176	-0.011	0.107	-0.176	-0.011	0.107
position:	1622	468342.04	-0.153	-0.022	0.130	-0.153	-0.022	0.130
position:	1623	468357.15	-0.157	0.036	0.126	-0.157	0.036	0.126
position:	1624	468372.55	-0.102	0.032	0.111	-0.102	0.032	0.111
position:	1625	468388.44	-0.062	0.073	0.146	-0.062	0.073	0.146
position:	1593	467781.66	0.051	0.030	-0.085	0.051	0.030	-0.085
position:	1594	467794.56	0.056	0.000	-0.040	0.056	0.000	-0.040
position:	1595	467807.55	0.085	0.033	-0.001	0.085	0.033	-0.001
position:	1596	467820.26	0.109	-0.035	-0.005	0.109	-0.035	-0.005
position:	1597	467832.85	0.093	-0.013	0.015	0.093	-0.013	0.014

position:	1598	467845.36	0.102	-0.024	0.053	0.102	-0.024	0.053
position:	1599	467857.74	0.103	-0.011	0.026	0.104	-0.011	0.026
position:	1600	467869.85	0.077	-0.005	0.014	0.077	-0.005	0.014
position:	1601	467881.95	0.098	0.006	0.009	0.098	0.006	0.009
position:	1602	467894.04	0.103	-0.042	0.041	0.103	-0.042	0.041
position:	1603	467906.23	0.060	0.009	-0.009	0.060	0.009	-0.009
position:	1604	467918.34	0.066	-0.003	0.050	0.067	-0.003	0.050
position:	1605	467930.56	0.064	0.003	0.037	0.064	0.003	0.037
position:	1606	467942.84	0.047	-0.033	0.064	0.047	-0.033	0.064

Average position offset:  
 East: 0.000 m  
 North: 0.000 m  
 Alt: 0.000 m  
 Position offset RMS:  
 East: 0.122 m  
 North: 0.031 m  
 Alt: 0.084 m

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## Misalignment angles for the single events [deg]:

	number	time	roll	pitch	yaw	d roll	d pitch	d yaw
angle:	1789	470968.30	0.0011	-0.0056	0.0058	0.0014	-0.0011	0.0054
angle:	1790	470982.99	0.0015	-0.0063	0.0071	0.0017	-0.0019	0.0067
angle:	1791	470997.80	-0.0011	-0.0069	0.0074	-0.0009	-0.0025	0.0070
angle:	1792	471012.55	-0.0016	-0.0078	0.0073	-0.0013	-0.0034	0.0069
angle:	1793	471027.59	-0.0013	-0.0070	0.0081	-0.0011	-0.0026	0.0077
angle:	1794	471042.88	-0.0013	-0.0079	0.0084	-0.0010	-0.0034	0.0080
angle:	1795	471058.28	-0.0023	-0.0083	0.0082	-0.0021	-0.0038	0.0078
angle:	1796	471073.79	-0.0027	-0.0070	0.0081	-0.0025	-0.0025	0.0077
angle:	1797	471089.19	-0.0020	-0.0071	0.0079	-0.0018	-0.0026	0.0075
angle:	1798	471104.97	-0.0026	-0.0080	0.0077	-0.0023	-0.0035	0.0073
angle:	1799	471120.38	-0.0024	-0.0063	0.0069	-0.0022	-0.0018	0.0065
angle:	1800	471135.37	-0.0029	-0.0072	0.0071	-0.0026	-0.0028	0.0067
angle:	1801	471150.59	-0.0037	-0.0076	0.0072	-0.0034	-0.0031	0.0068
angle:	1772	470587.58	0.0068	-0.0023	-0.0068	0.0071	0.0021	-0.0072
angle:	1773	470600.19	0.0062	-0.0043	-0.0057	0.0065	0.0001	-0.0061
angle:	1774	470612.77	0.0055	-0.0047	-0.0047	0.0057	-0.0003	-0.0051
angle:	1775	470625.59	0.0052	-0.0054	-0.0034	0.0054	-0.0010	-0.0038
angle:	1776	470638.16	0.0064	-0.0049	-0.0027	0.0066	-0.0004	-0.0031
angle:	1777	470650.88	0.0051	-0.0057	-0.0019	0.0053	-0.0012	-0.0023
angle:	1778	470663.17	0.0043	-0.0060	-0.0007	0.0045	-0.0016	-0.0011
angle:	1779	470675.07	0.0036	-0.0052	-0.0002	0.0038	-0.0007	-0.0006
angle:	1780	470687.17	0.0040	-0.0054	0.0005	0.0043	-0.0010	0.0001
angle:	1781	470699.16	0.0032	-0.0049	0.0014	0.0035	-0.0004	0.0010
angle:	1782	470711.36	0.0031	-0.0065	0.0027	0.0034	-0.0020	0.0023
angle:	1783	470723.55	0.0031	-0.0051	0.0035	0.0033	-0.0006	0.0031
angle:	1784	470735.66	0.0029	-0.0046	0.0046	0.0031	-0.0002	0.0043
angle:	1613	468207.07	-0.0028	-0.0001	0.0009	-0.0026	0.0043	0.0005
angle:	1614	468221.97	-0.0027	-0.0032	0.0011	-0.0025	0.0012	0.0007
angle:	1615	468236.98	-0.0042	-0.0032	-0.0003	-0.0040	0.0013	-0.0006
angle:	1616	468251.87	-0.0030	-0.0043	-0.0001	-0.0027	0.0001	-0.0005
angle:	1617	468266.78	-0.0030	-0.0033	-0.0002	-0.0027	0.0012	-0.0006
angle:	1618	468281.77	-0.0042	-0.0046	-0.0010	-0.0039	-0.0001	-0.0014
angle:	1619	468296.96	-0.0037	-0.0046	-0.0013	-0.0035	-0.0001	-0.0017
angle:	1620	468311.95	-0.0043	-0.0045	-0.0016	-0.0040	0.0000	-0.0020
angle:	1621	468326.85	-0.0040	-0.0038	-0.0016	-0.0037	0.0006	-0.0020
angle:	1622	468342.04	-0.0051	-0.0041	-0.0016	-0.0048	0.0003	-0.0020
angle:	1623	468357.15	-0.0053	-0.0041	-0.0016	-0.0051	0.0003	-0.0020
angle:	1624	468372.55	-0.0062	-0.0035	-0.0015	-0.0059	0.0009	-0.0019
angle:	1625	468388.44	-0.0062	-0.0037	-0.0022	-0.0060	0.0008	-0.0025
angle:	1593	467781.66	0.0024	-0.0010	-0.0074	0.0026	0.0034	-0.0078
angle:	1594	467794.56	0.0021	-0.0007	-0.0070	0.0024	0.0037	-0.0074
angle:	1595	467807.55	0.0009	-0.0012	-0.0062	0.0012	0.0032	-0.0066
angle:	1596	467820.26	0.0016	-0.0018	-0.0058	0.0018	0.0027	-0.0062
angle:	1597	467832.85	-0.0001	-0.0020	-0.0056	0.0002	0.0025	-0.0060
angle:	1598	467845.36	0.0001	-0.0018	-0.0049	0.0003	0.0026	-0.0053
angle:	1599	467857.74	-0.0002	-0.0030	-0.0048	0.0000	0.0015	-0.0052
angle:	1600	467869.85	0.0002	-0.0018	-0.0043	0.0005	0.0026	-0.0047
angle:	1601	467881.95	-0.0010	-0.0023	-0.0033	-0.0008	0.0021	-0.0037
angle:	1602	467894.04	0.0002	-0.0028	-0.0023	0.0004	0.0017	-0.0027
angle:	1603	467906.23	-0.0002	-0.0028	-0.0011	0.0000	0.0017	-0.0015
angle:	1604	467918.34	-0.0005	-0.0026	-0.0007	-0.0002	0.0018	-0.0011
angle:	1605	467930.56	-0.0012	-0.0035	0.0002	-0.0009	0.0009	-0.0001
angle:	1606	467942.84	-0.0005	-0.0037	0.0014	-0.0003	0.0007	0.0010

Average Boresight Angles:  
 Roll: 0.1419 deg  
 Pitch: 0.2883 deg  
 Yaw: -0.2896 deg  
 Boresight Angle RMS:  
 Roll: 0.0034 deg  
 Pitch: 0.0021 deg  
 Yaw: 0.0048 deg

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Success!!  
 Boresight Calculation finished