

Camera Calibration Certificate  
No: DMC III 27541



For

**ICGC – Institut Cartogràfic i Geològic de  
Catalunya**

Parc de Montjuïc, S/N  
Barcelona 08038

Spain

This calibration certificate complies with DIN 18740-4

Camera: DMC III  
Manufacturer: Leica Geosystems Technologies, D-73430 Aalen, Germany  
Reference: PAN  
Serial Number: 00128300 (PAN Head)  
Date of Calibration: 26. May 2017  
Date of Report: 26. May 2017  
Number of Pages: 48

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This camera system is certified by Leica Geosystems Technologies and is fully functional within its specifications and tolerances.

Date of Calibration: May 2017

Date of Certification: May 2017



Dipl.Ing. Christian Mueller, Product Manager

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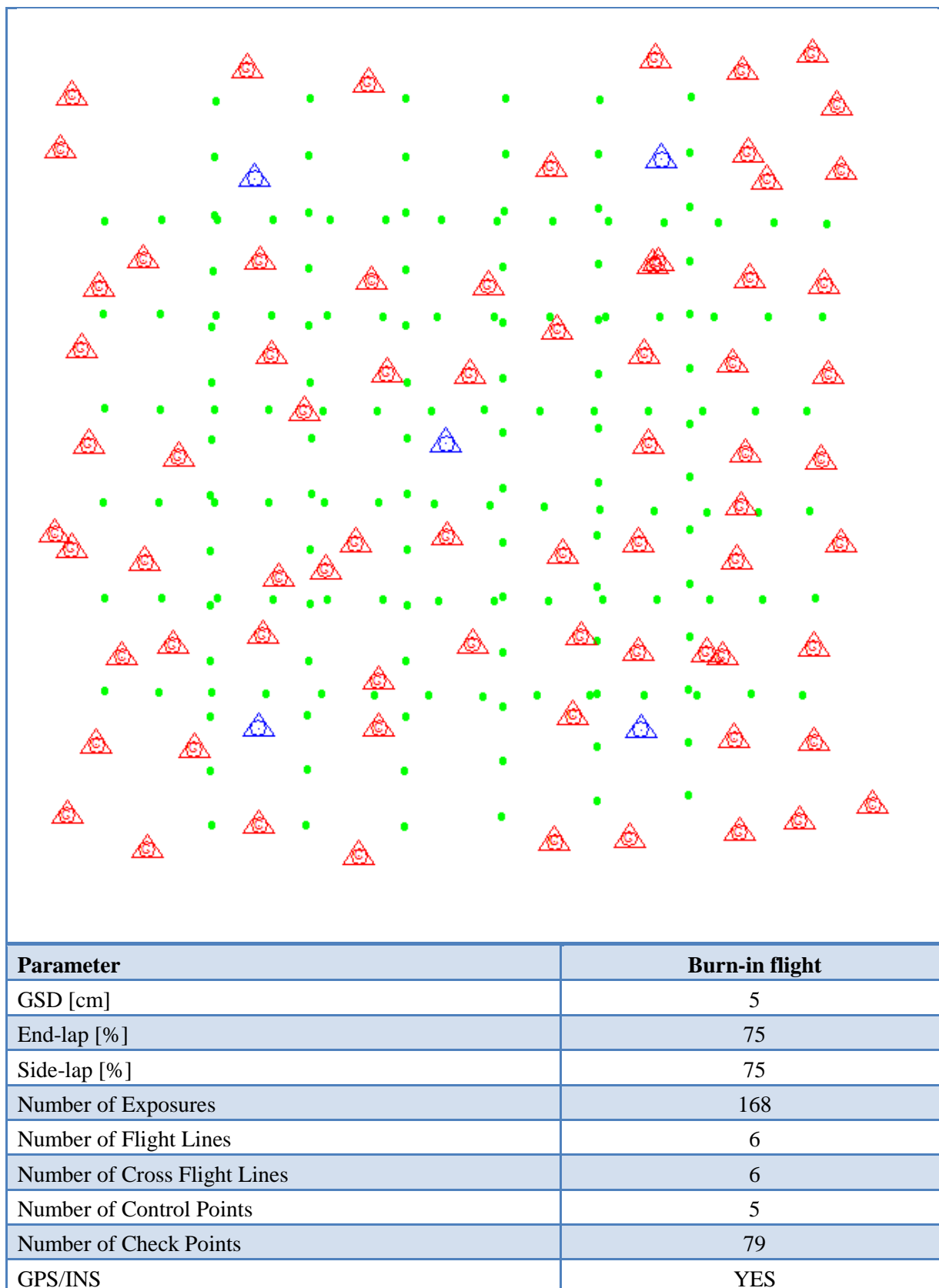
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## Camera Serial Numbers and Calibration flight

Camera Head	Serial Number	Calib. Date
PAN (reference)	00128300	26.05.2017
MS1 (NIR)	00128322	26.05.2017
MS2 (Blue)	00128348	26.05.2017
MS3 (Red)	00128321	26.05.2017
MS4 (Green)	00128348	26.05.2017

Calibration flight performed: 23. May 2017

### Flight parameters of 5cm Calibration Flight



## Application

Parameter	Burn-in flight
Weighting for manual measured image points	1.0
Weighting for automatic measured image points	1.0
Weighting for Control Points	2.8 / 2.8 / 1.6
Weighting for GPS	1.6 / 1.6 / 1.6
Weighting for INS	0.2 / 0.2 / 0.1
Modeling of GPS systematic residuals	NO
Bore Sight Alignment (YES/NO)	NO
Camera Self Calibration (YES/NO)	NO

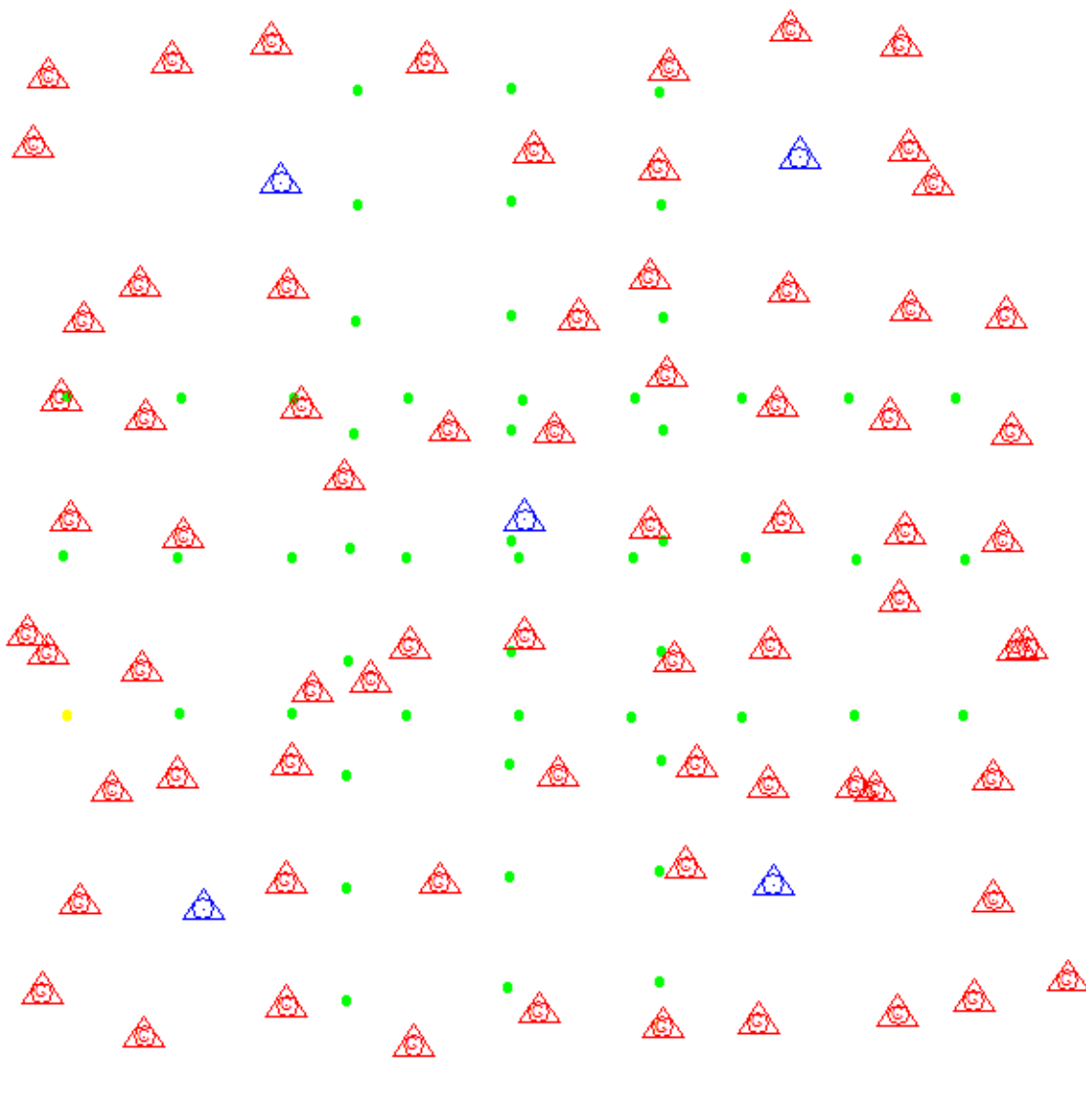
## Statistics – Bundleblockadjustment

Parameter	Burn-in flight
Sigma0 [ $\mu\text{m}$ ]	1.312
Mean Std Dev Photo Position [cm]	1.2 / 1.2 / 0.4
Mean Std Dev Photo Attitude [mdeg]	0.5 / 0.6 / 0.2
Mean Std Dev Control Points [cm]	0.5 / 0.5 / 1.0
Mean Std Dev Check Points [cm]	0.7 / 0.7 / 1.8
RMS Photo Position [cm]	1.0 / 1.1 / 1.0
RMS Photo Attitude [mdeg]	0.9 / 0.9 / 1.6

## Statistics – Results

Parameter	Burn-in flight
RMS of Control Points – horizontal [cm]	1.5 / 2.5
Max Ground Residual of Control Points – horizontal [cm]	3.1 / 3.8
RMS of Control Points – vertical [cm]	2.7
Max Ground Residual of Control Points – vertical [cm]	3.7
RMS of Check Points – horizontal [cm]	1.5 / 2.8
Max Ground Residual of Check Points – horizontal [cm]	3.4 / 5.8
RMS of Check Points – vertical [cm]	3.9
Max Ground Residual of Check Points – vertical [cm]	7.9

### Flight parameters of independent 8cm Reference Block

	
Parameter	Burn-in flight
GSD [cm]	8
End-lap [%]	70
Side-lap [%]	60
Number of Exposures	54
Number of Flight Lines	3
Number of Cross Flight Lines	3
Number of Control Points	5
Number of Check Points	87
GPS/INS	YES

## Application

Parameter	Burn-in flight
Weighting for manual measured image points	1.0
Weighting for automatic measured image points	1.0
Weighting for Control Points	7.1 / 7.1 / 4.0
Weighting for GPS	4.0 / 4.0 / 4.0
Weighting for INS	0.2 / 0.2 / 0.1
Modeling of GPS systematic residuals	NO
Bore Sight Alignment (YES/NO)	NO
Camera Self Calibration (YES/NO)	NO

## Statistics – Bundleblockadjustment

Parameter	Burn-in flight
Sigma0 [ $\mu\text{m}$ ]	1.051
Mean Std Dev Photo Position [cm]	1.2 / 1.1 / 0.5
Mean Std Dev Photo Attitude [mdeg]	0.3 / 0.4 / 0.3
Mean Std Dev Control Points [cm]	0.6 / 0.6 / 1.1
Mean Std Dev Check Points [cm]	1.0 / 1.0 / 2.7
RMS Photo Position [cm]	1.3 / 1.1 / 1.5
RMS Photo Attitude [mdeg]	1.0 / 1.0 / 1.2

## Statistics – Results from independent Referenceblock

Parameter	Burn-in flight
RMS of Control Points – horizontal [cm]	0.9 / 1.5
Max Ground Residual of Control Points – horizontal [cm]	1.5 / 2.8
RMS of Control Points – vertical [cm]	0.9
Max Ground Residual of Control Points – vertical [cm]	1.9
RMS of Check Points – horizontal [cm]	2.3 / 2.4
Max Ground Residual of Check Points – horizontal [cm]	5.3 / 4.2
RMS of Check Points – vertical [cm]	4.2
Max Ground Residual of Check Points – vertical [cm]	8.7

The results of the aerial triangulation were generated with ImageStation Automatic Triangulation (ISAT), 2016, from Intergraph Inc.. The maximum RMS in check points is  $\leq 0.5$  GSD in x,y and  $\leq 0.7$  GSD in z.

Aerial Triangulation performed by



Dipl. Ing. Christian Mueller

26.05.2017

Date

## Geometric Calibration

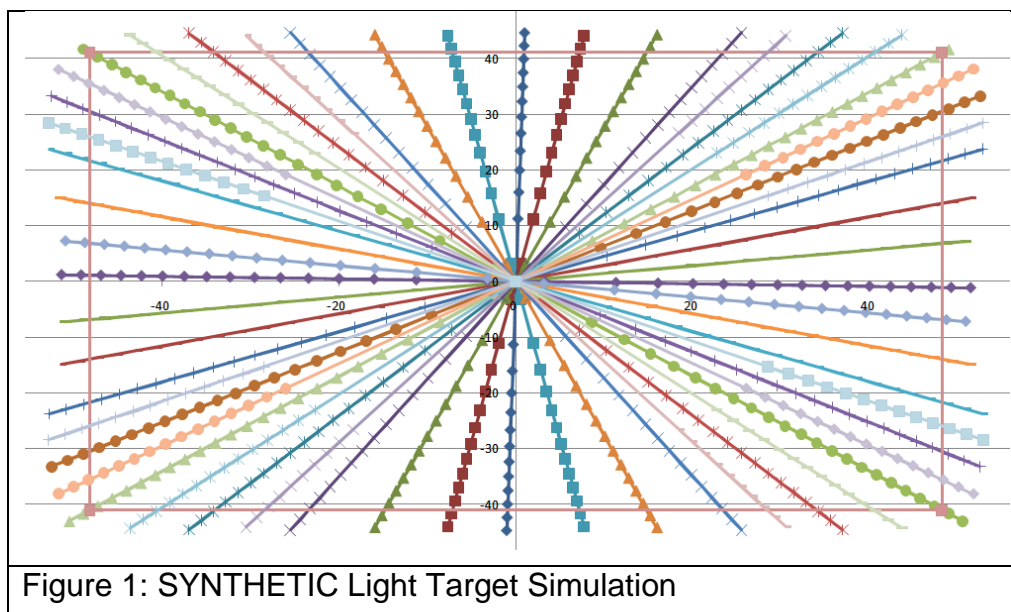
The output image geometry is based on the Pan Camera head (reference head = master camera). All other camera heads are registered and aligned to this head. Aerial triangulation checks overall system performance based on.

## Output image

Reference Camera	PAN	
Serial Number	00128300	
Number of rows/columns [pixels]	25728 x 14592	
Pixel Size [ $\mu\text{m}$ ]	3.900 x 3.900	
Image Size [mm]	100.3392 x 56.9088	
Focal Length [mm]	92.0000 mm	+ /- 0.001 mm
Principal Point [mm]	X= 0.0000 mm, Y= 0.0000 mm	+ /- 0.001 mm

The “SYNTHETIC” geometric calibration is based on a simulated mathematical lens distortion calculation based on the detailed optical design data of the lens.

It is equivalent to the DMC II collimator calibration procedure, projecting 800 “light targets” on 28 lines that are distributed diagonally on the focal plane.





# Geometric Calibration

## Image Residuals

Figure 2 shows the image residuals, split in radial and tangential directions after the calibration adjustment. The maximum residuals are less than or equal to 1.0 microns and the RMSE values are below 0.5 microns.

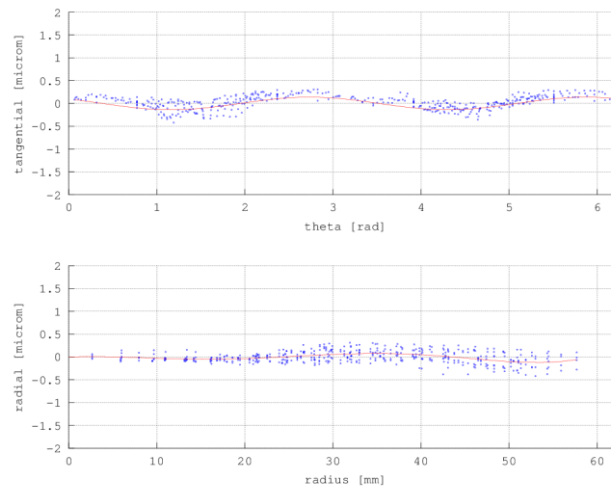


Figure 2: Tangential/Radial Distortion Residuals

Figure 3 shows the 2-D plot of the image residuals in  $\mu\text{m}$ .

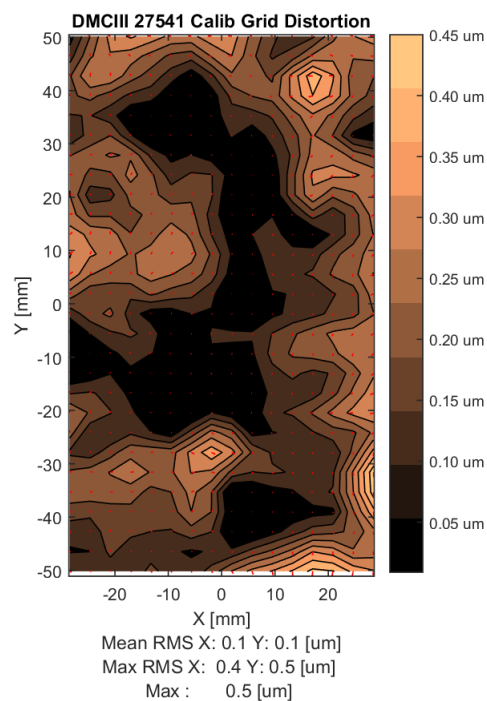


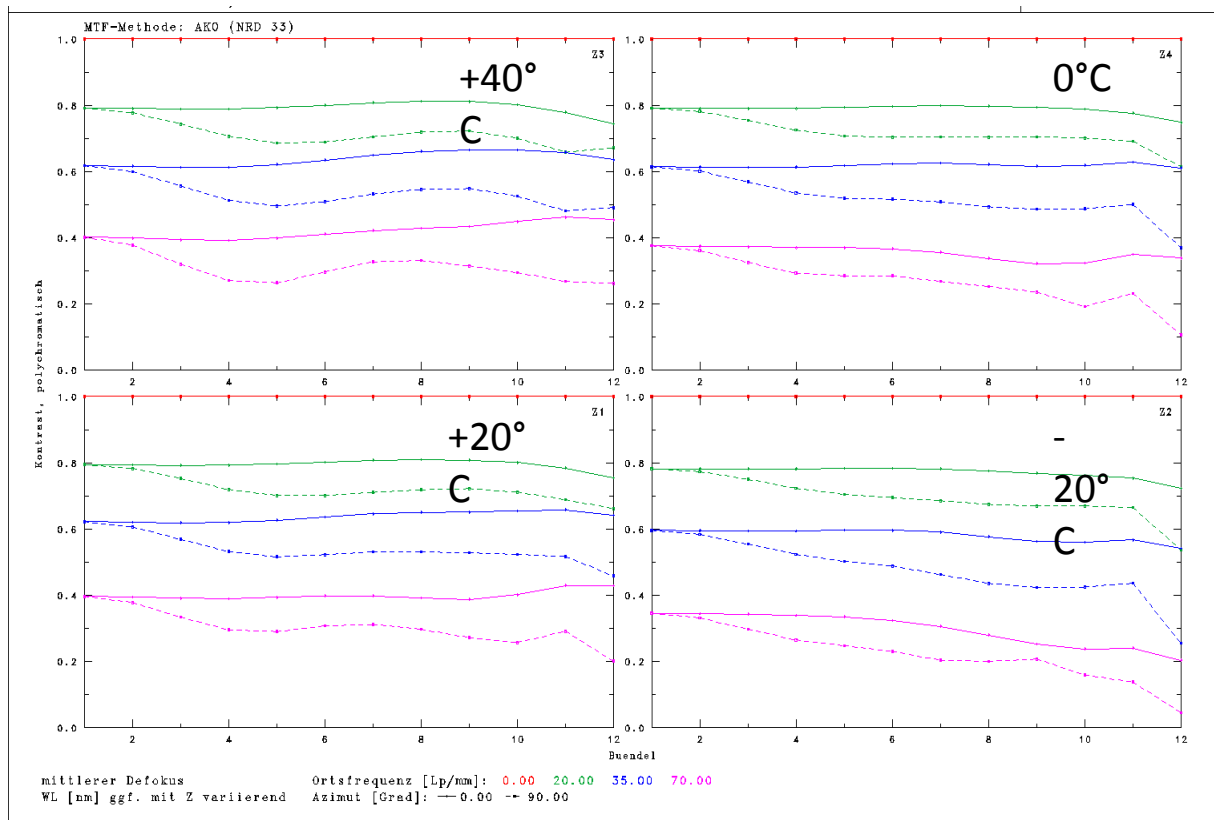
Figure 3: 2-D Image Residuals.

Mean RMS  $\leq 0.2 \mu\text{m}$  (maximum 0.5 microns)

# Optical System

## Modulation Transfer Function, MTF of PAN Camera (Reference)

DMC III PAN – MTF Polychromatic F/5.6 ; 92 mm – Temperature Stability

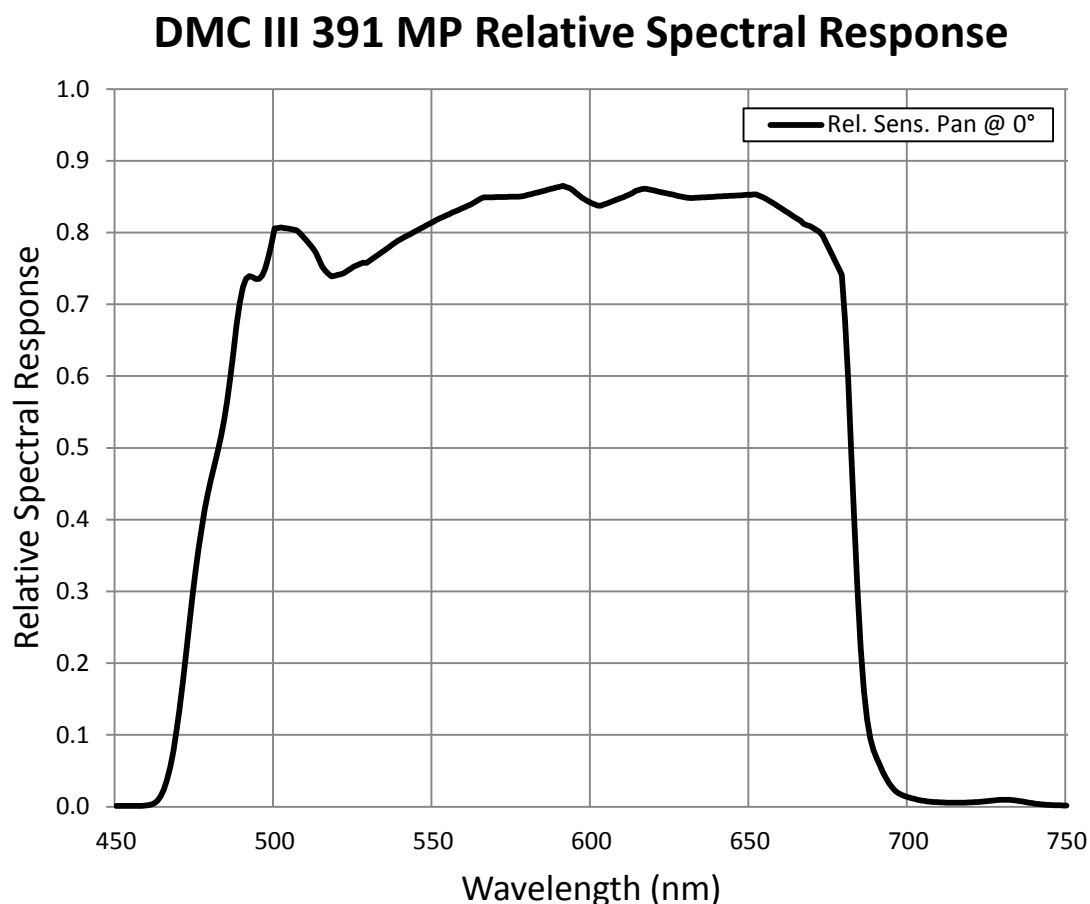


The MTF measurement is camera type specific and shows variation of the MTF within the specified temperature range.

This is a camera type specific measurement.

## Radiometric Calibration

### Sensitivity of PAN camera (Reference)



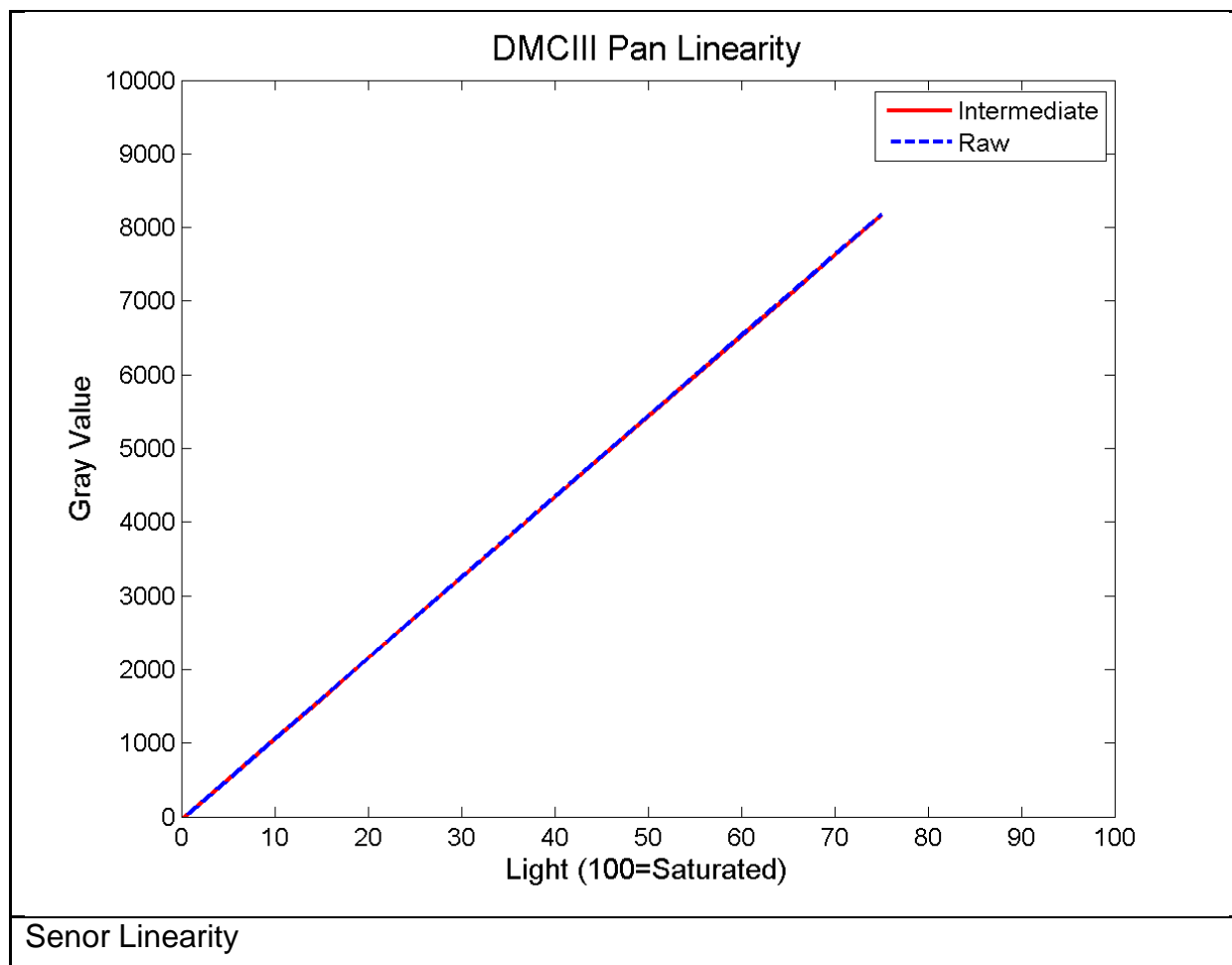
The sensitivity shows the spectral response curve of the single camera head including the optical system (optics, filter) and the sensor response. The DMC III is calibrated with a NIST traceable spectroradiometer and an integrating sphere. . This allows computing pixel radiance values from pixels digital numbers and is a camera type specific calibration.

This is a camera type specific measurement.

## Sensor Linearity (Reference)

The sensor linearity is measured in the Lab with calibrated spectrometer. This is a camera type specific calibration.

Below figure shows the linearity of the raw sensor and after flat fielding:



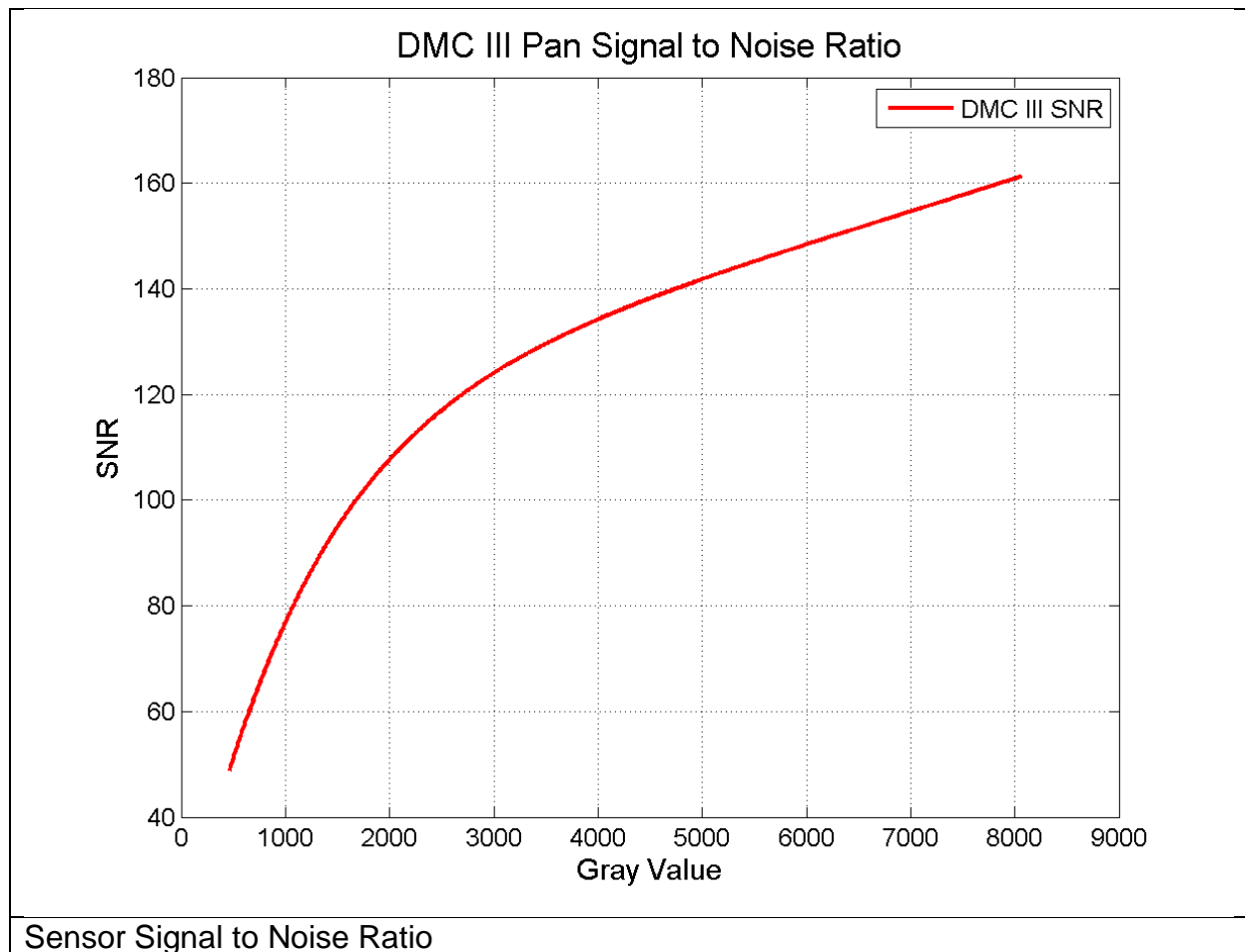
The deviation from the linearity is below 1%.

This is a camera type specific measurement.

# Radiometric Calibration

## Sensor Noise (Reference)

Sensor noise shows image noise with respect to the image center measured at an aperture of 16 with exposure time of 16msec.



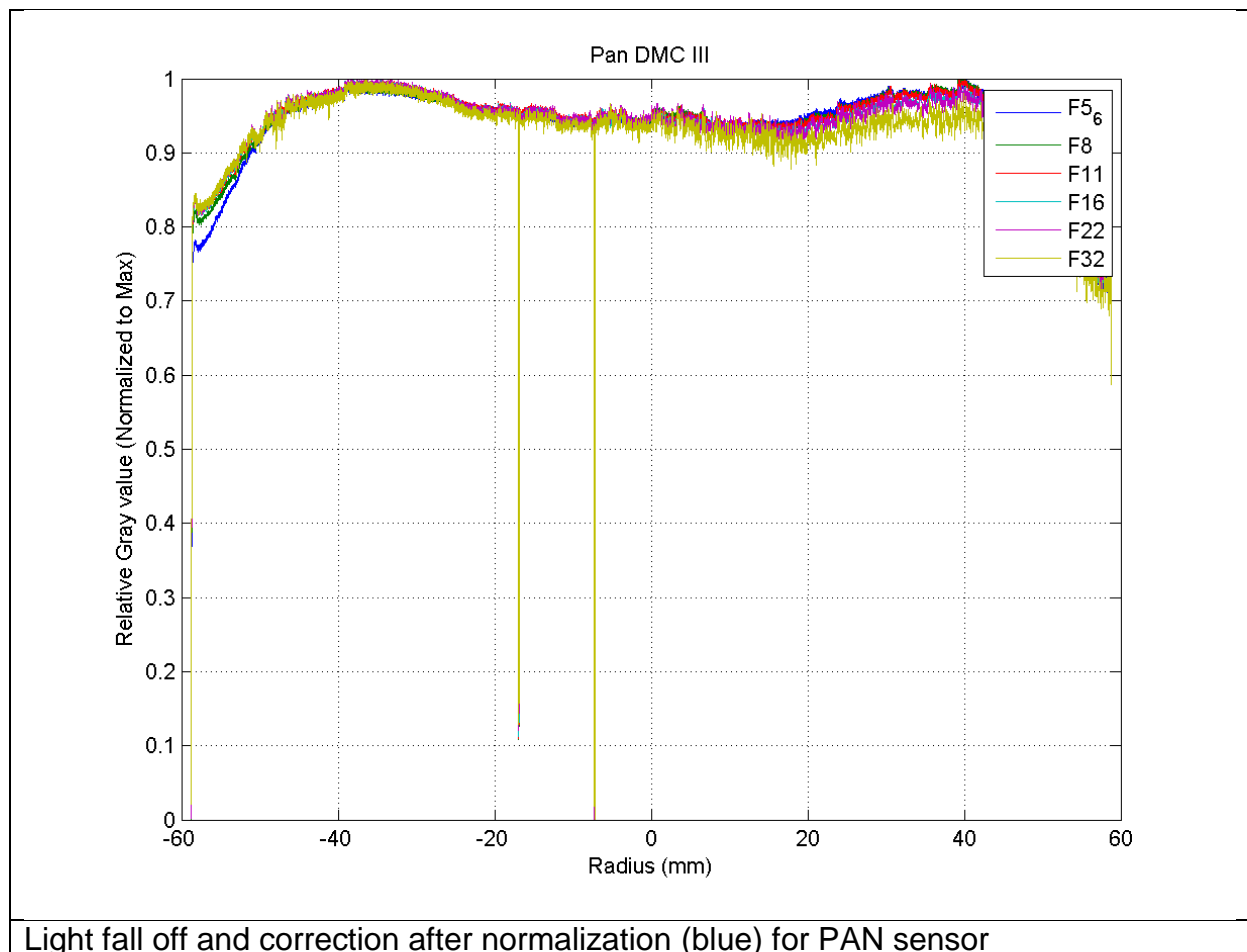
This is from a camera type specific calibration.

# Radiometric Calibration

## Aperture Correction (Reference)

### Camera PAN (00128300)

The light fall off to the border due the influence of the optics depends on the aperture used. Therefore this calibration approach delivers individual calibration images for each aperture (Full F-Stop). In general the light fall off is a function of the image height (radial distance from center). The figure below shows the profile from the upper left corner to the lower right corner of the calibration images. Compensation of the light fall off can be measured after normalization and is within  $\pm 2.5\%$  of the dynamic range.



This is from a camera type specific calibration.

# Radiometric Calibration

## Defect Pixel

### Camera PAN (00128300)

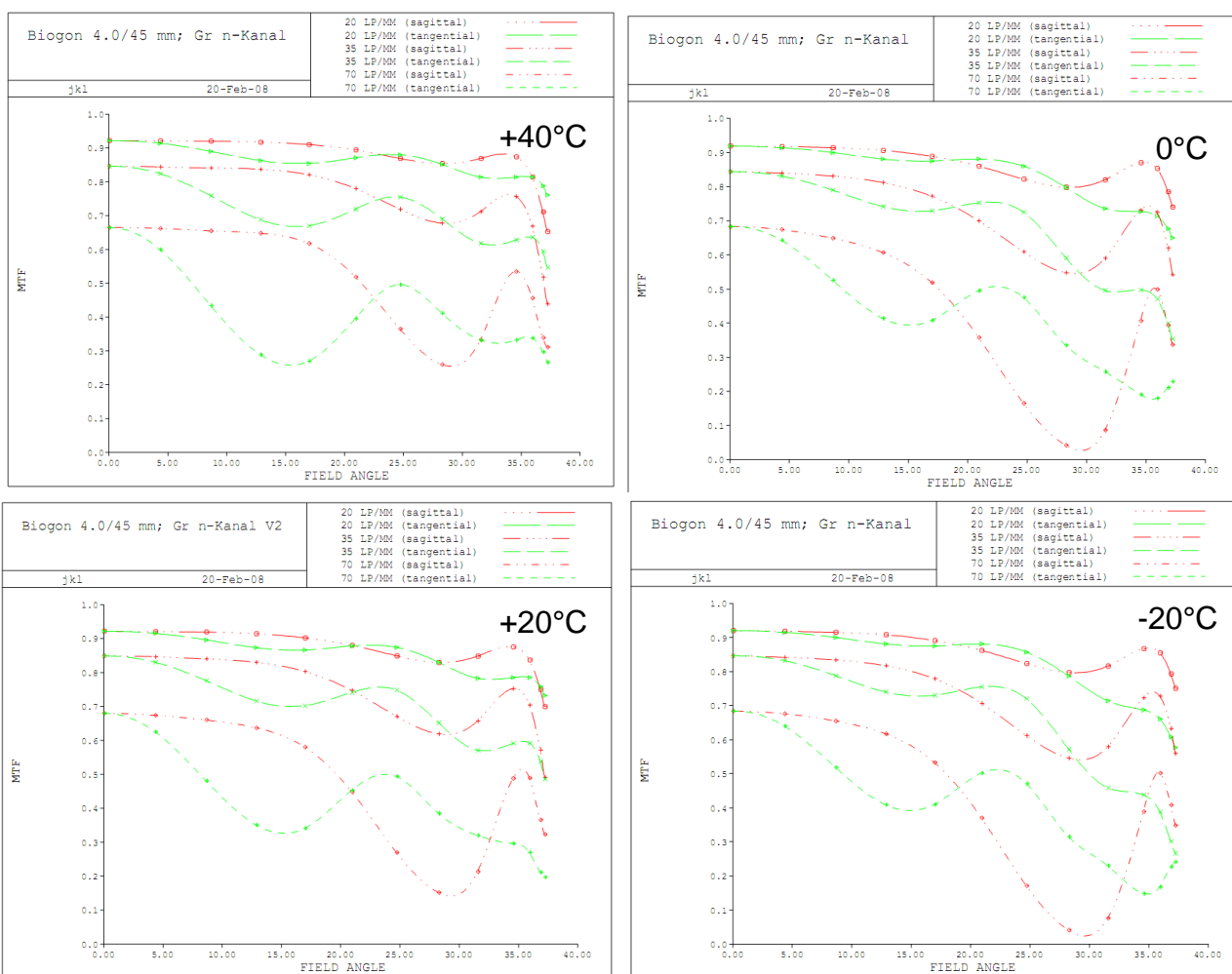
Defect pixels are detected during radiometric calibration and will be corrected during radiometric processing of the images.

The quantity and cumulative percentage and specification of defects are described in Appendix “Defect Pixel Recognition” at page 47.

# Optical System

## Modulation Transfer Function, MTF of Green camera

DMC III MS Green – MTF F/4.0 ; 45 mm– Temperature Stability

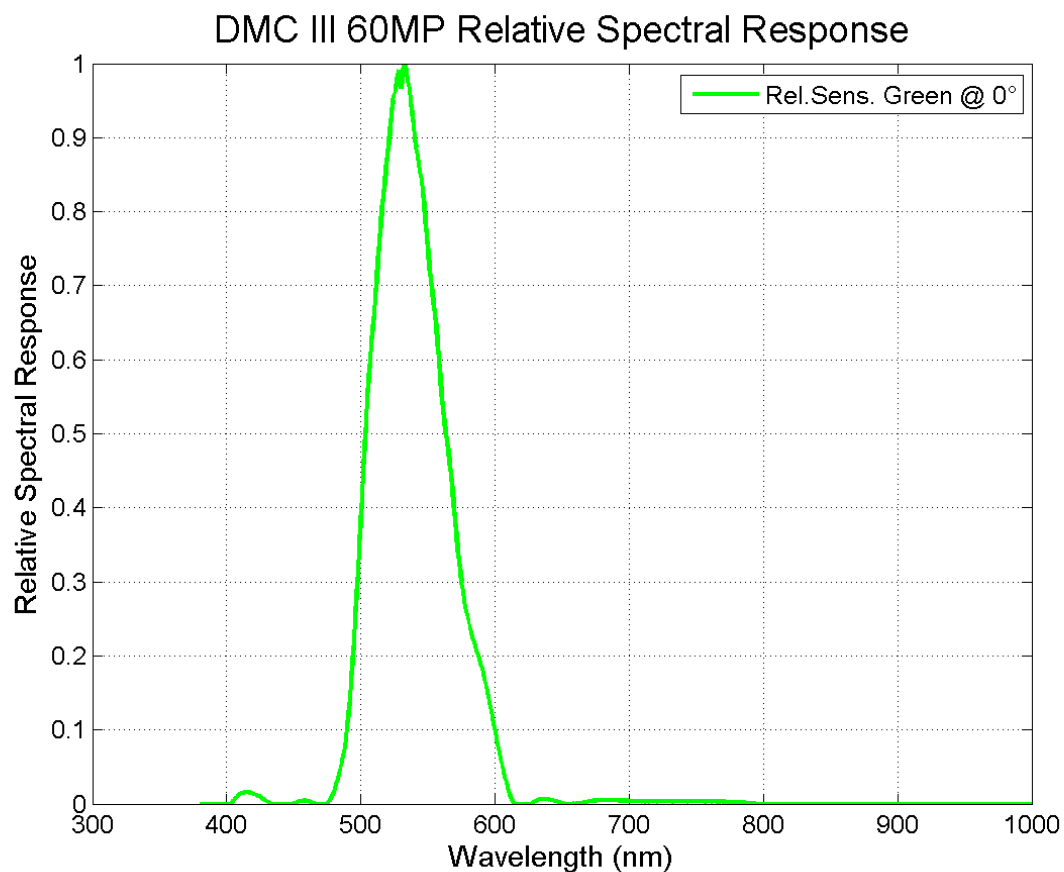




## Radiometric Calibration

### Sensitivity of Green camera

Spectral response curve of the single camera head.



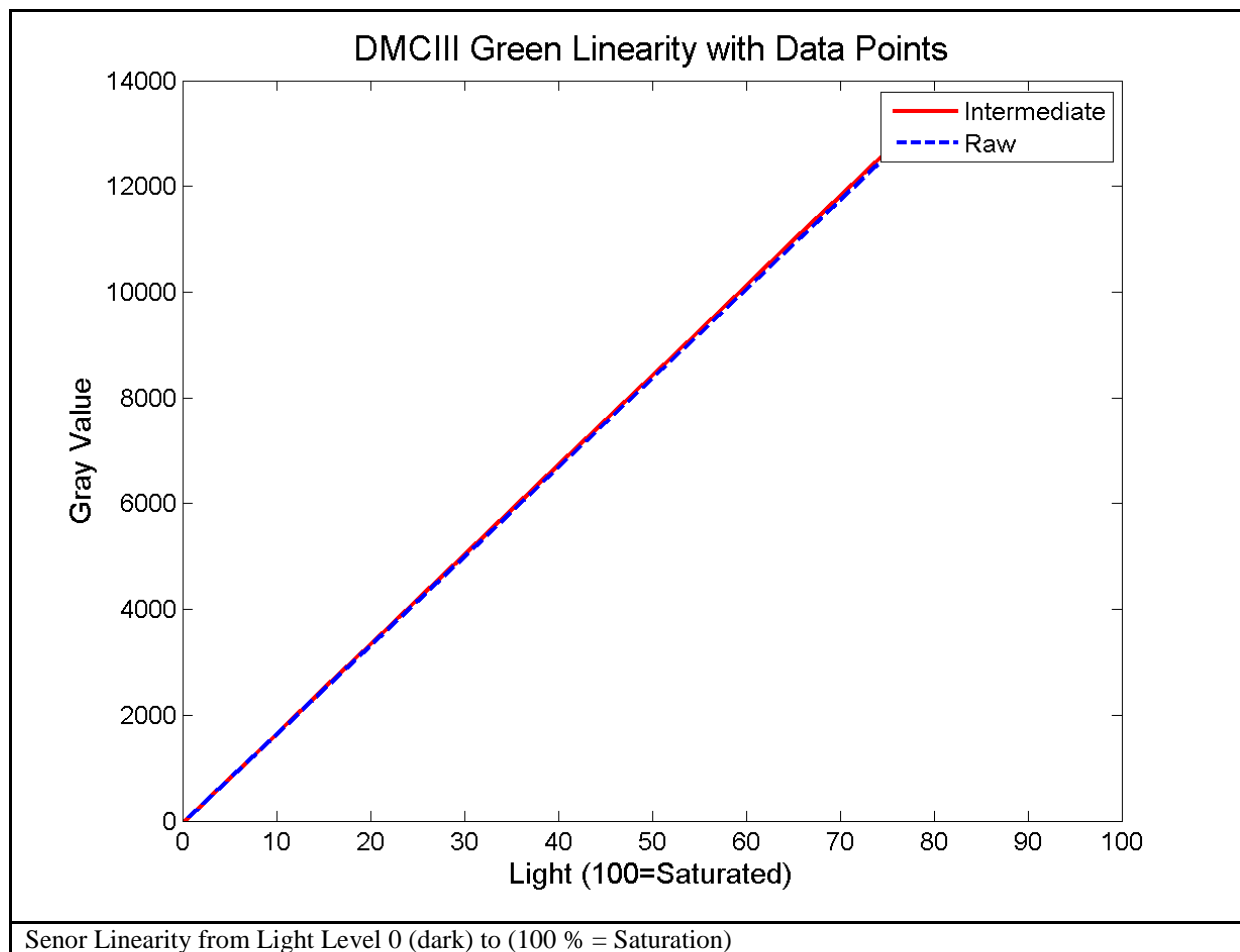
The sensitivity shows the spectral response curve of the single camera head including the optical system (optics, filter) and the sensor response. The DMC III is calibrated with respect to the absolute spectrometer. This allows computing pixel radiance values from pixels digital numbers and is a camera type specific calibration.

# Radiometric Calibration

## Sensor Linearity (Reference)

The sensor linearity is measured in the Lab with calibrated spectrometer. This is a camera type specific calibration.

Below figure shows the linearity of the raw sensor and after flat fielding:

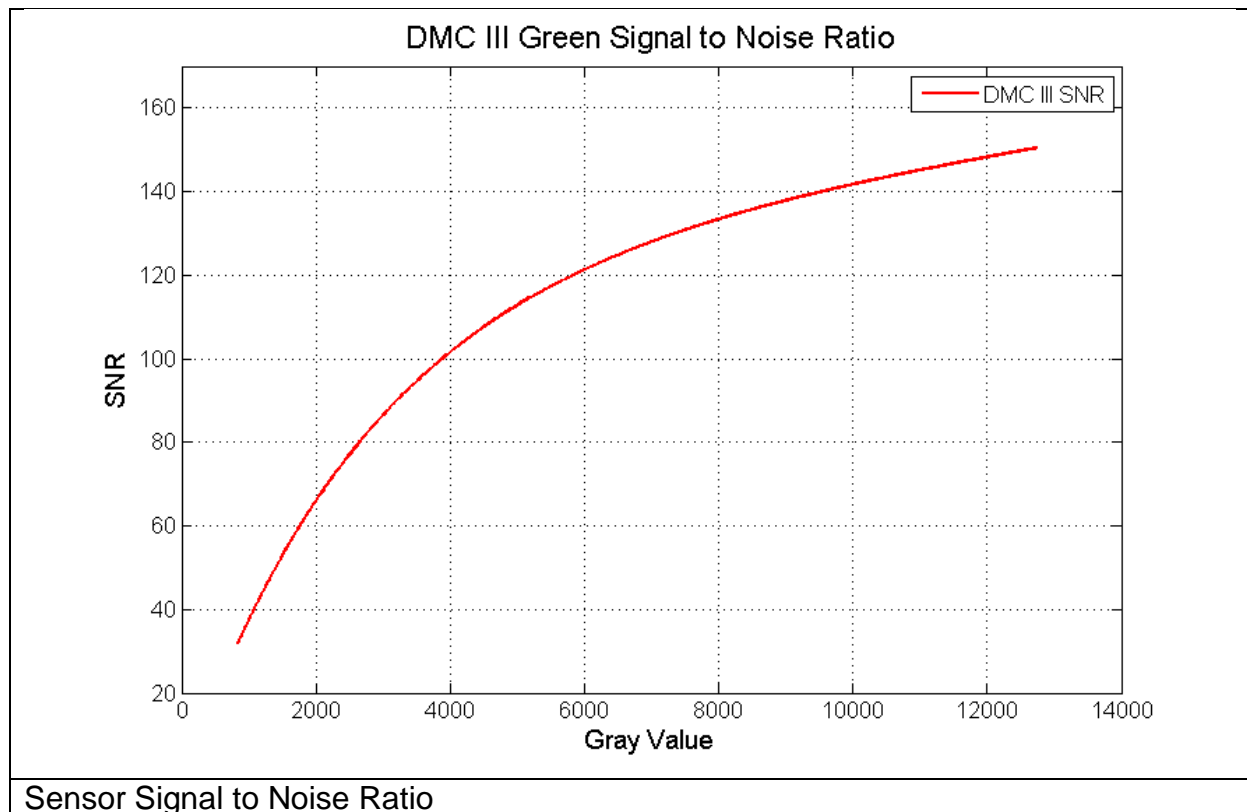


The deviation from the linearity is below 1%.

# Radiometric Calibration

## Sensor Noise (Reference)

Sensor noise shows image noise with respect to the image center measured at an aperture of 5.6 with exposure time of 10msec.

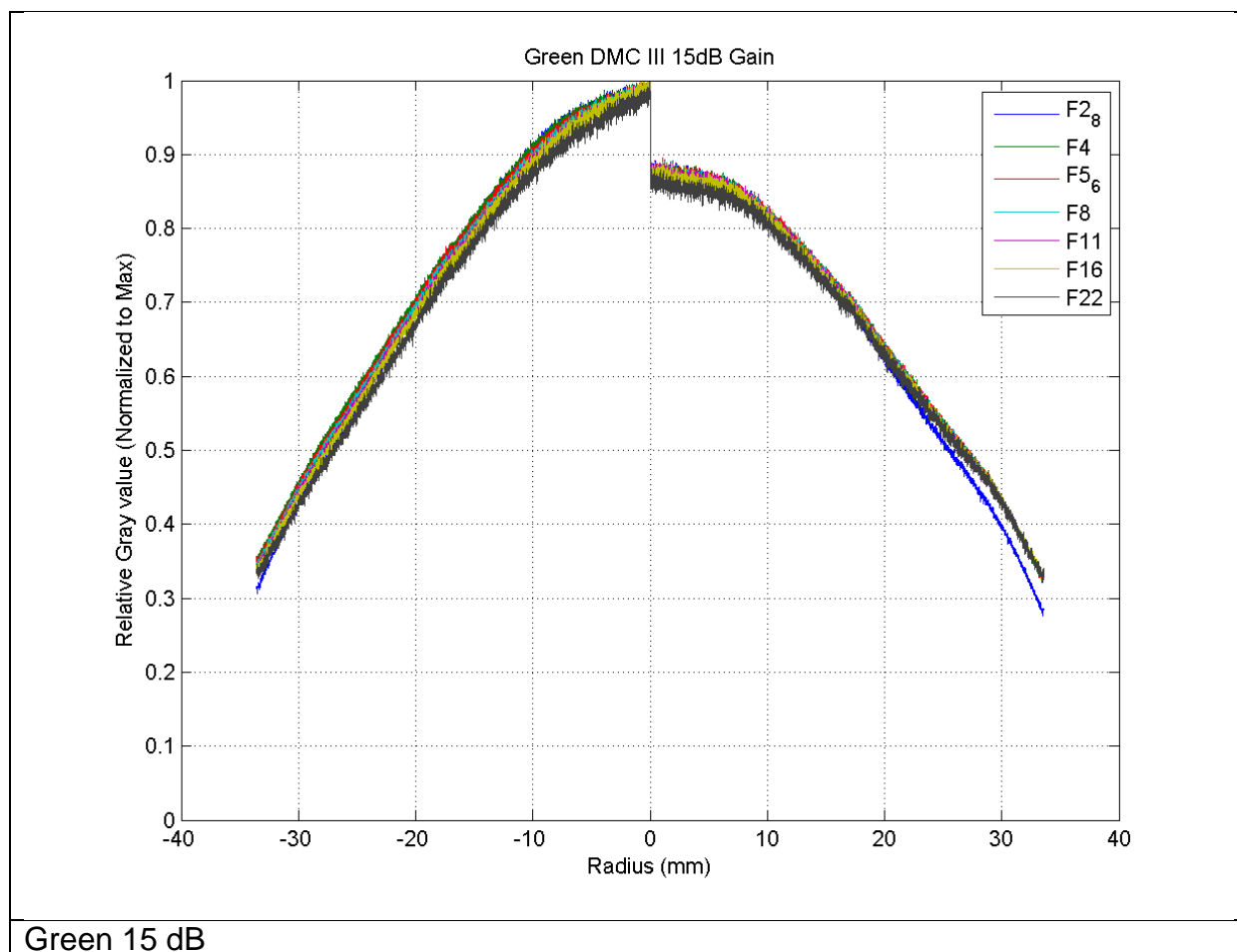


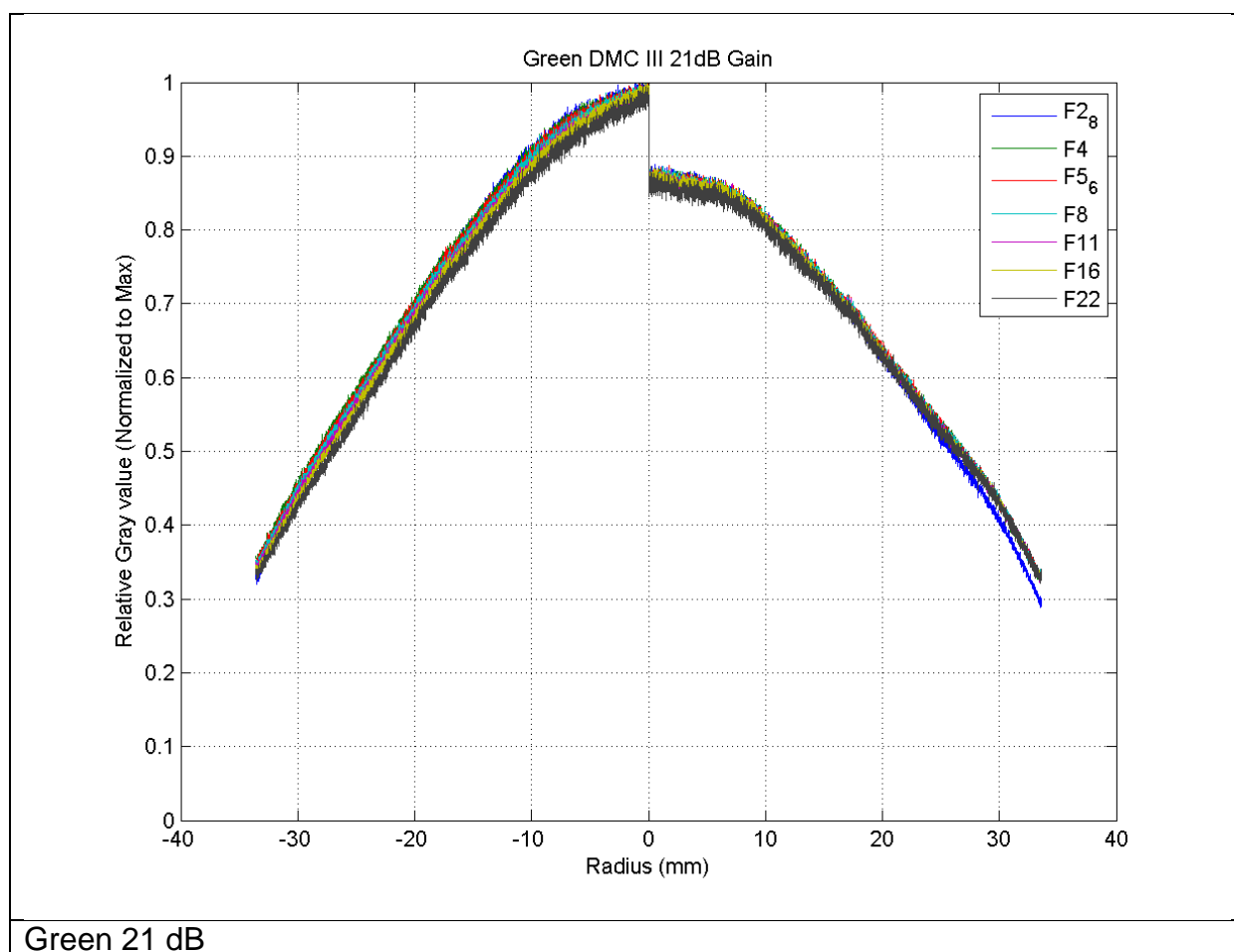
# Radiometric Calibration

## Aperture Correction

### Green (00128341)

The light fall off to the border due the influence of the optics depends on the aperture used. Therefore this calibration approach delivers individual calibration images for each aperture (Full F-Stop). In general the light fall off is a function of the image height (radial distance from center). The figure below shows the profile from the upper left corner to the lower right corner of the calibration images.





This is a camera type specific calibration.

# Radiometric Calibration

## Defect Pixel

### Green (00128341)

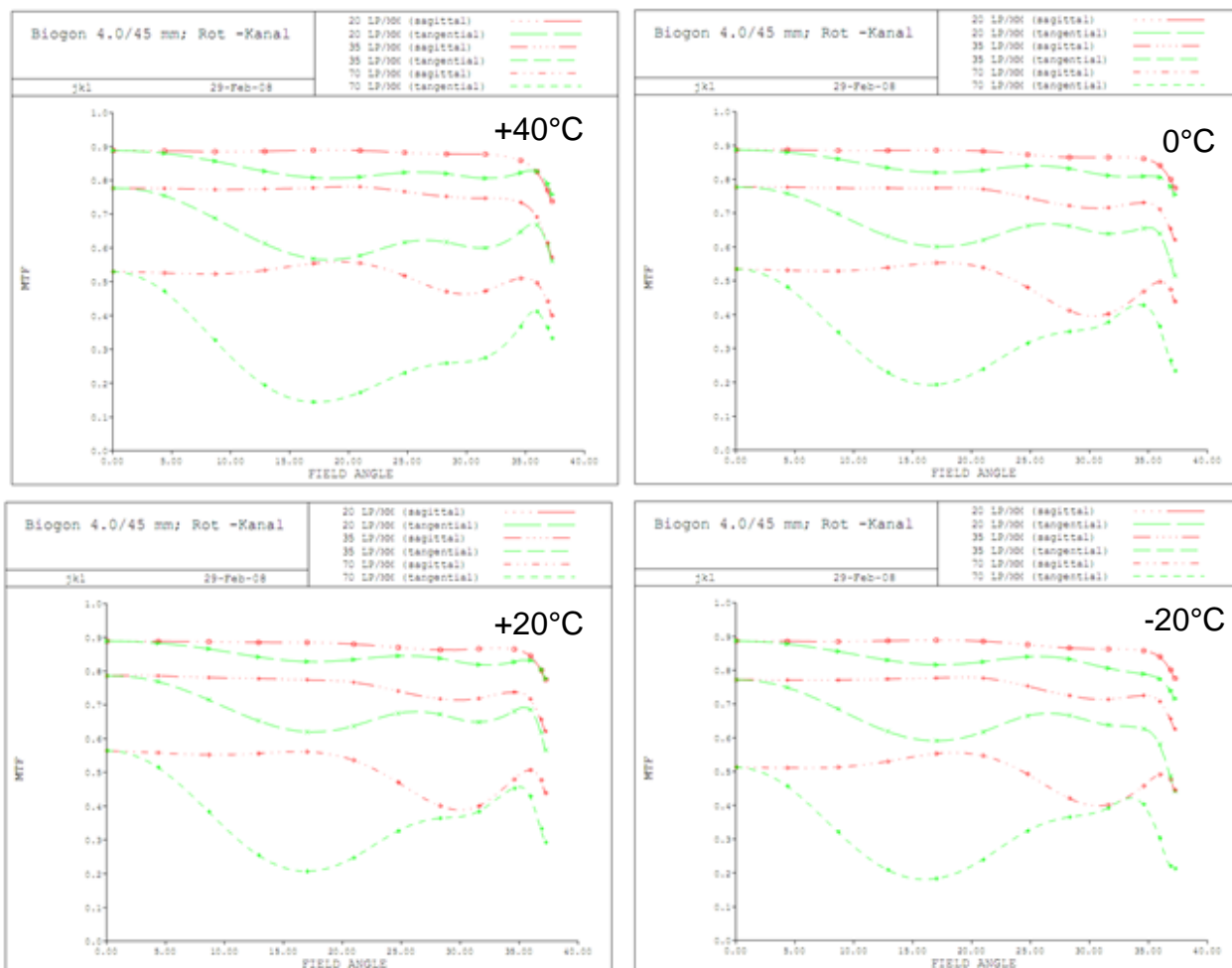
Defect pixels are detected during radiometric calibration and will be corrected during radiometric processing of the images.

The quantity and cumulative percentage and specification of defects are described in Appendix “Defect Pixel Recognition” at page 47.

# Optical System

## Modulation Transfer Function, MTF of Red camera

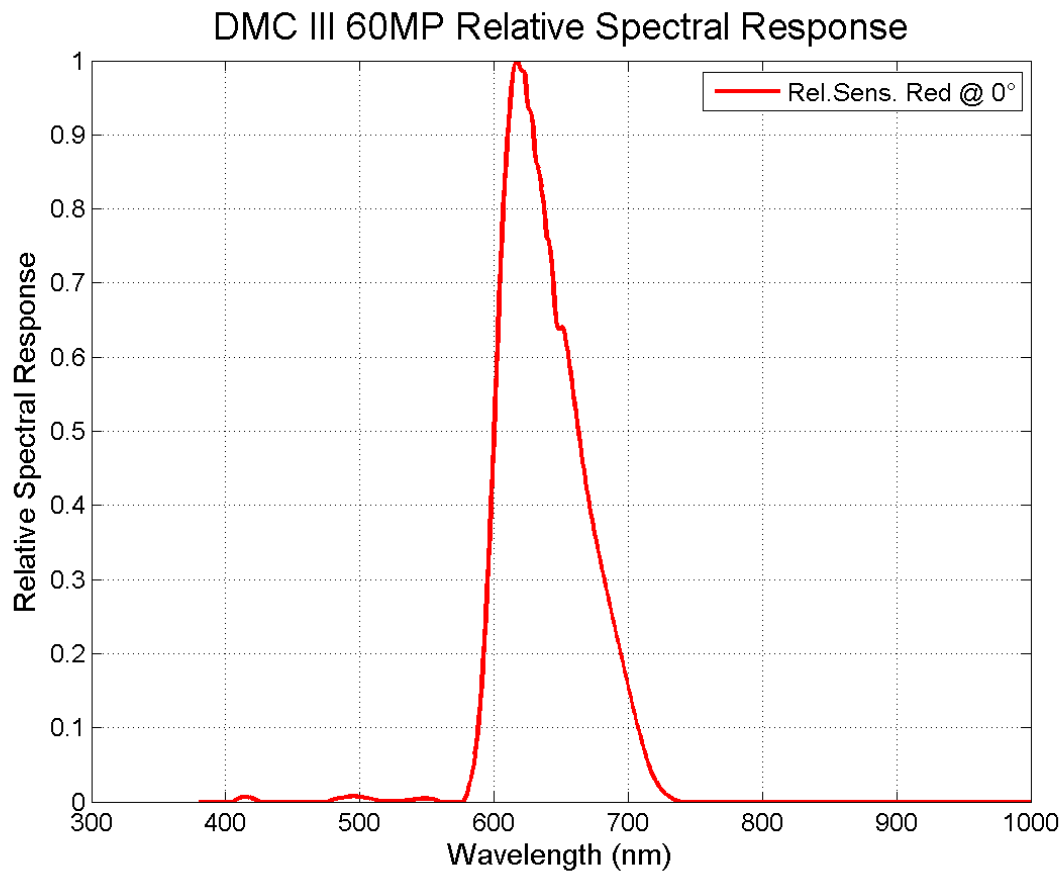
DMC III MS Red – MTF F/4.0 ; 45 mm– Temperature Stability



# Radiometric Calibration

## Sensitivity of Red camera

Spectral Response Curves of the single camera head.



The sensitivity shows the spectral response curve of the single camera head including the optical system (optics, filter) and the sensor response. The DMC III is calibrated with respect to the absolute spectrometer. This allows computing pixel radiance values from pixels digital numbers and is a camera type specific calibration.

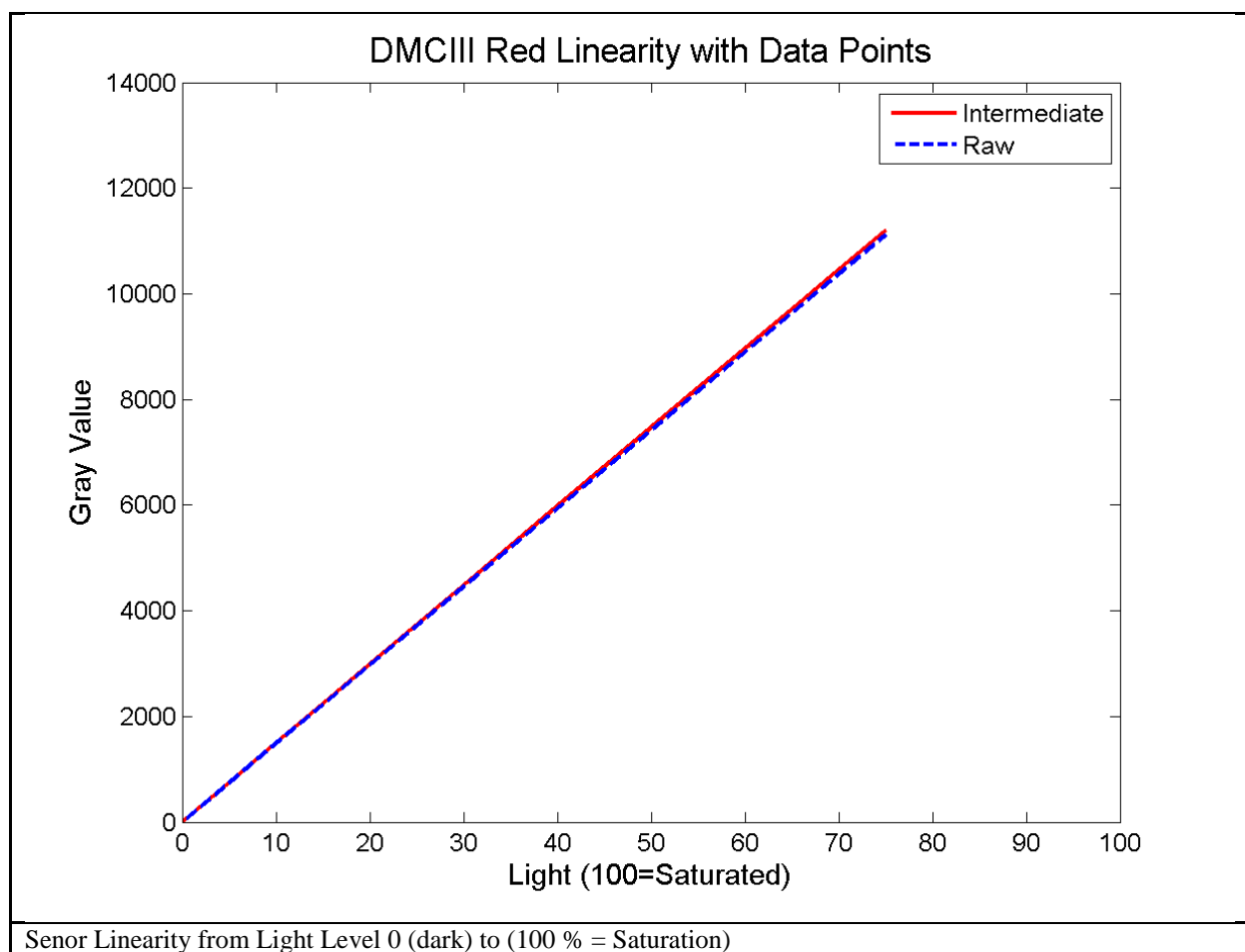


## Radiometric Calibration

### Sensor Linearity (Reference)

The sensor linearity is measured in the Lab with calibrated spectrometer. This is a camera type specific calibration.

Below figure shows the linearity of the raw sensor and after flat fielding:

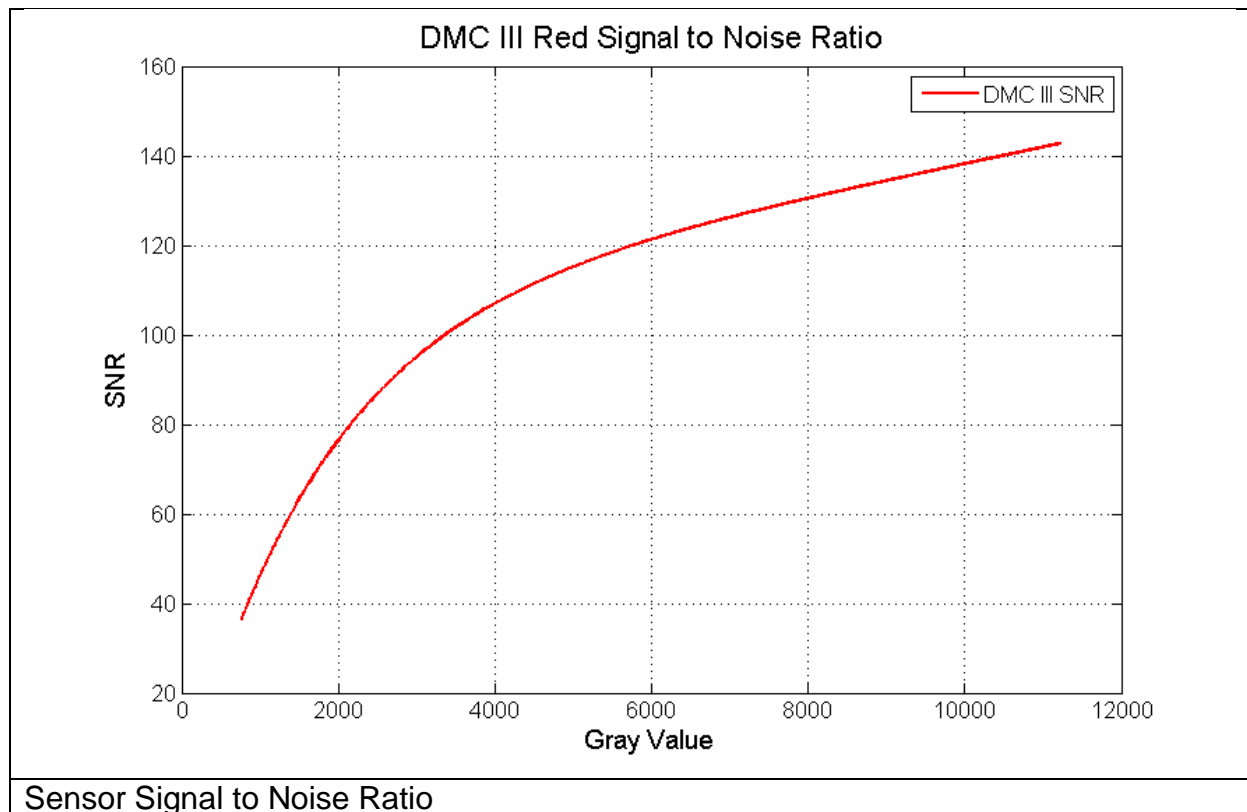


The deviation from the linearity is below 1%.

# Radiometric Calibration

## Sensor Noise (Reference)

Sensor noise shows image noise with respect to the image center measured at an aperture of 5.6 with exposure time of 10msec.

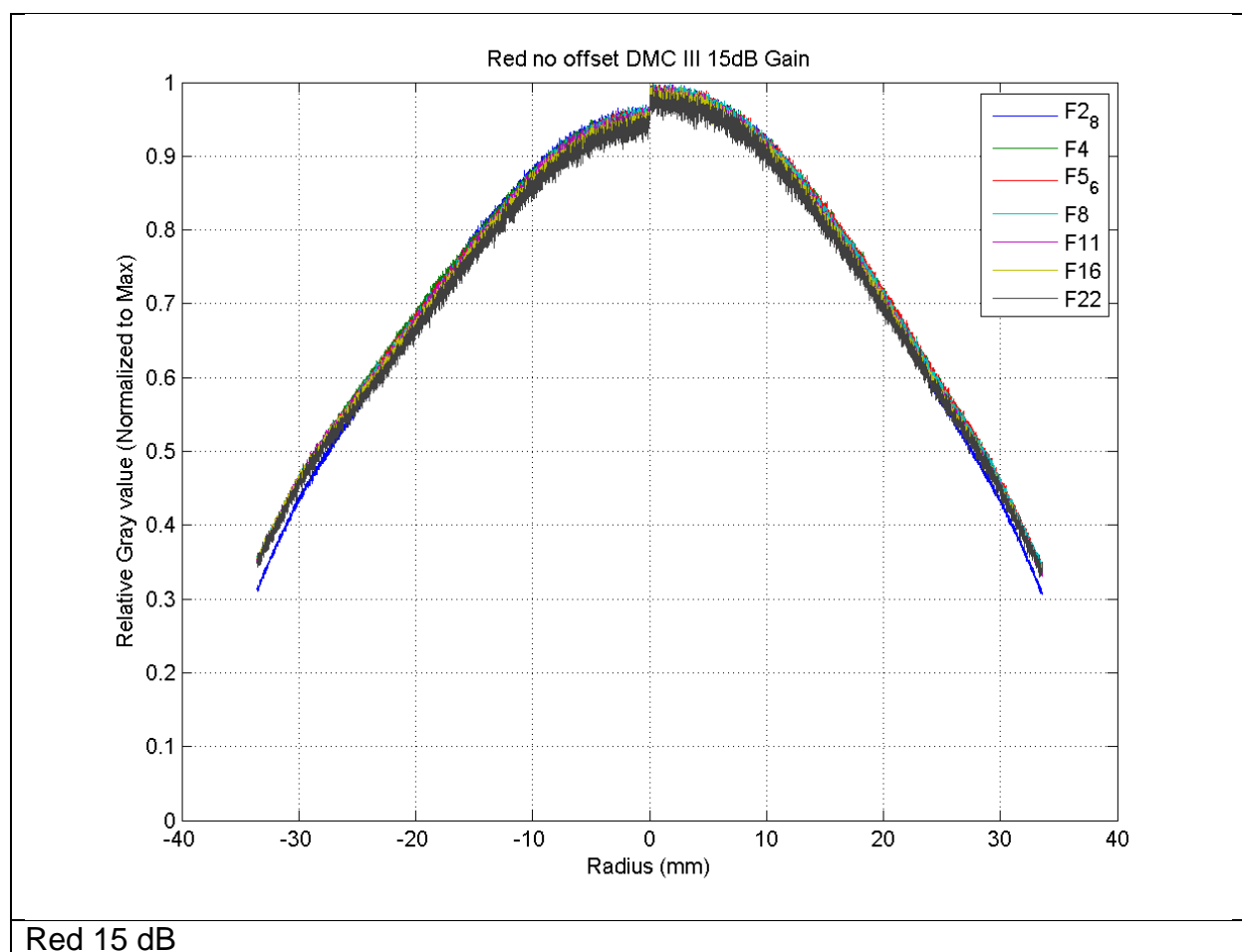


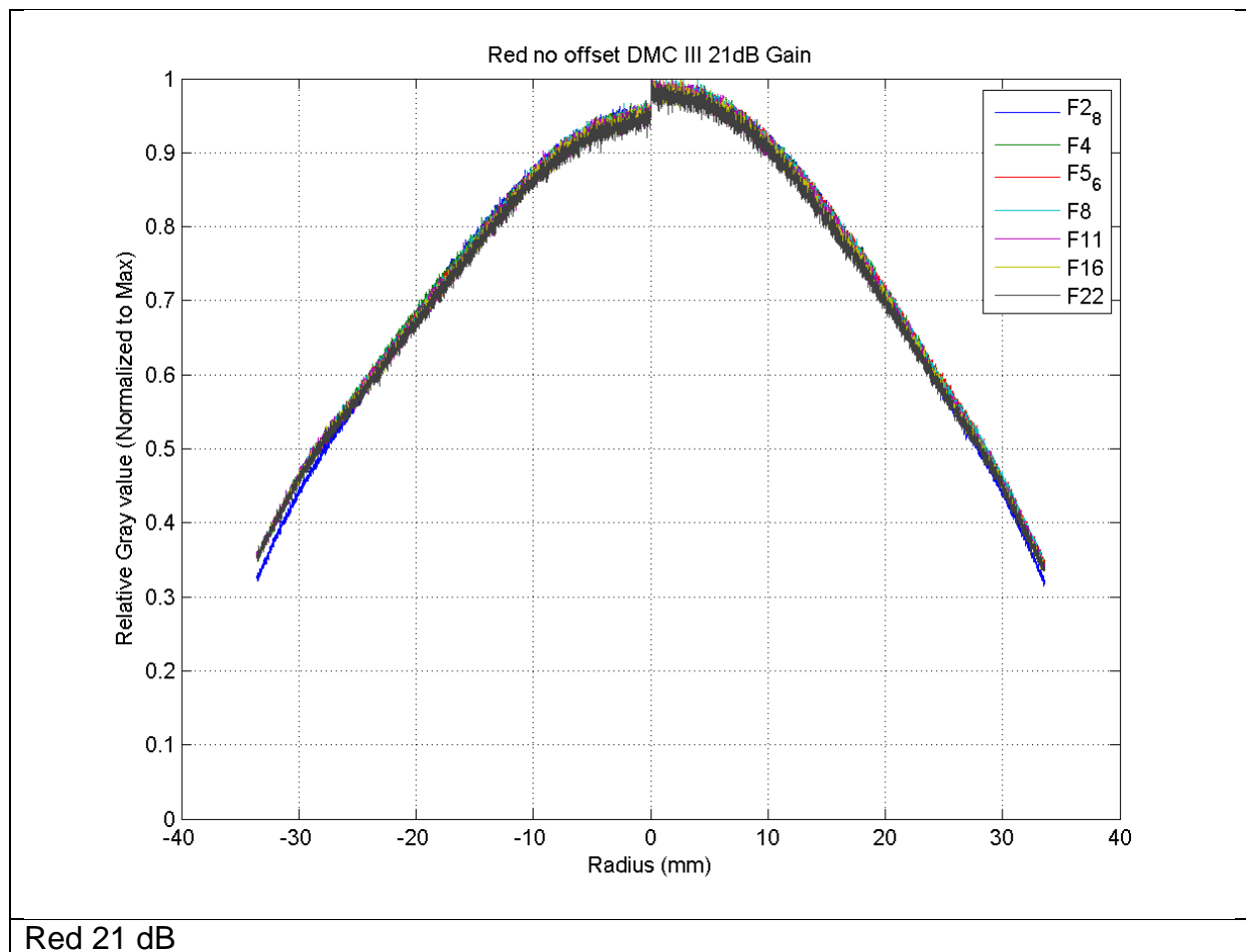
# Radiometric Calibration

## Aperture Correction

### Red (00128321)

The light fall off to the border due the influence of the optics depends on the used aperture. Therefore this calibration approach has for each aperture (Full F-Stop) its own calibration image. In general the light fall off is a function of the image radius. In this calibration approach instead of function the real measured values in the image is used. The figure below shows the profile from the upper left corner to the lower right corner of each of this calibration images to give a feeling on the amount of correction.





This is a camera type specific calibration.

# Radiometric Calibration

## Defect Pixel

### Red (00128321)

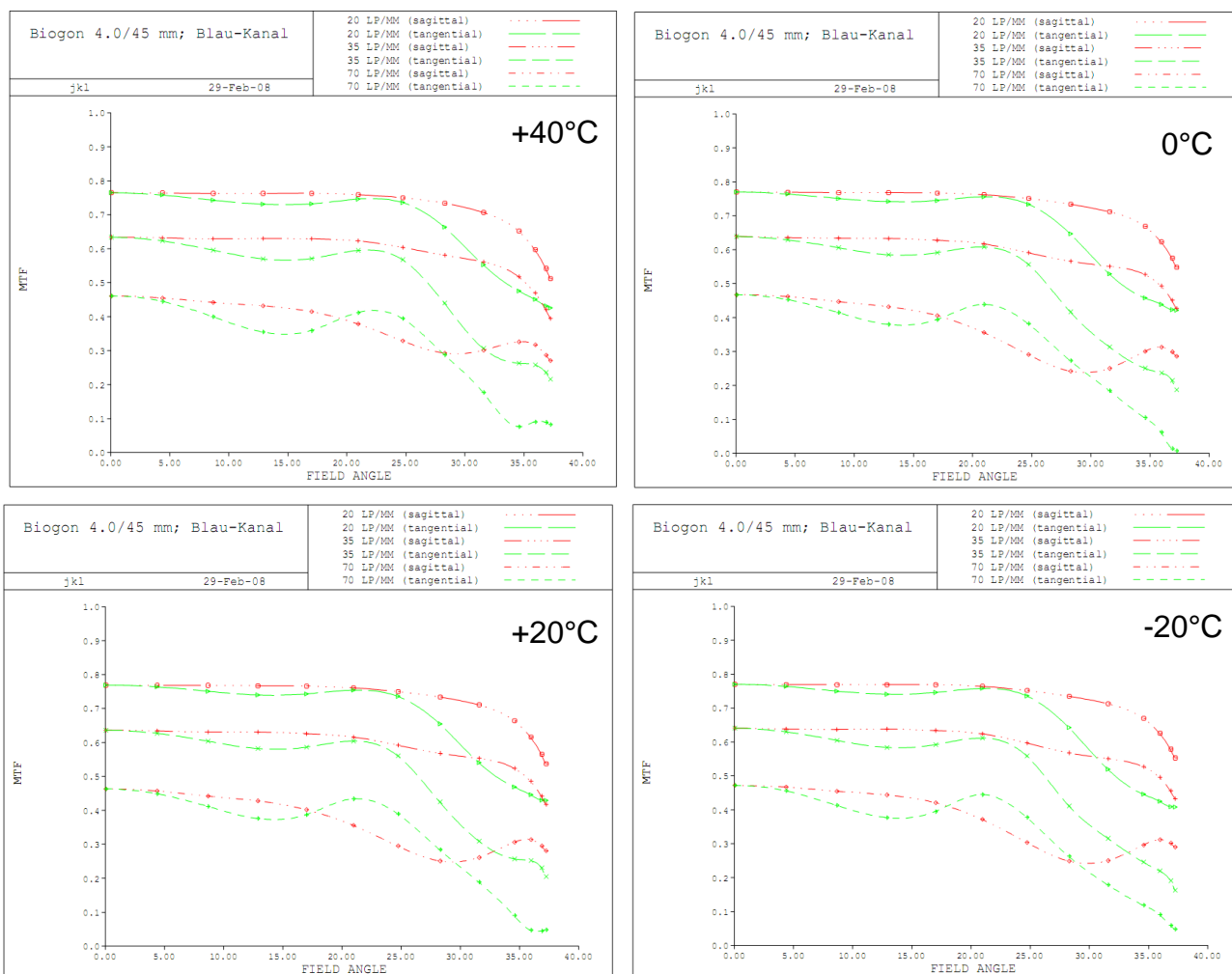
Defect pixels are detected during radiometric calibration and will be corrected during radiometric processing of the images.

The quantity and cumulative percentage and specification of defects are described in Appendix “Defect Pixel Recognition” at page 47.

# Optical System

## Modulation Transfer Function, MTF of Blue camera

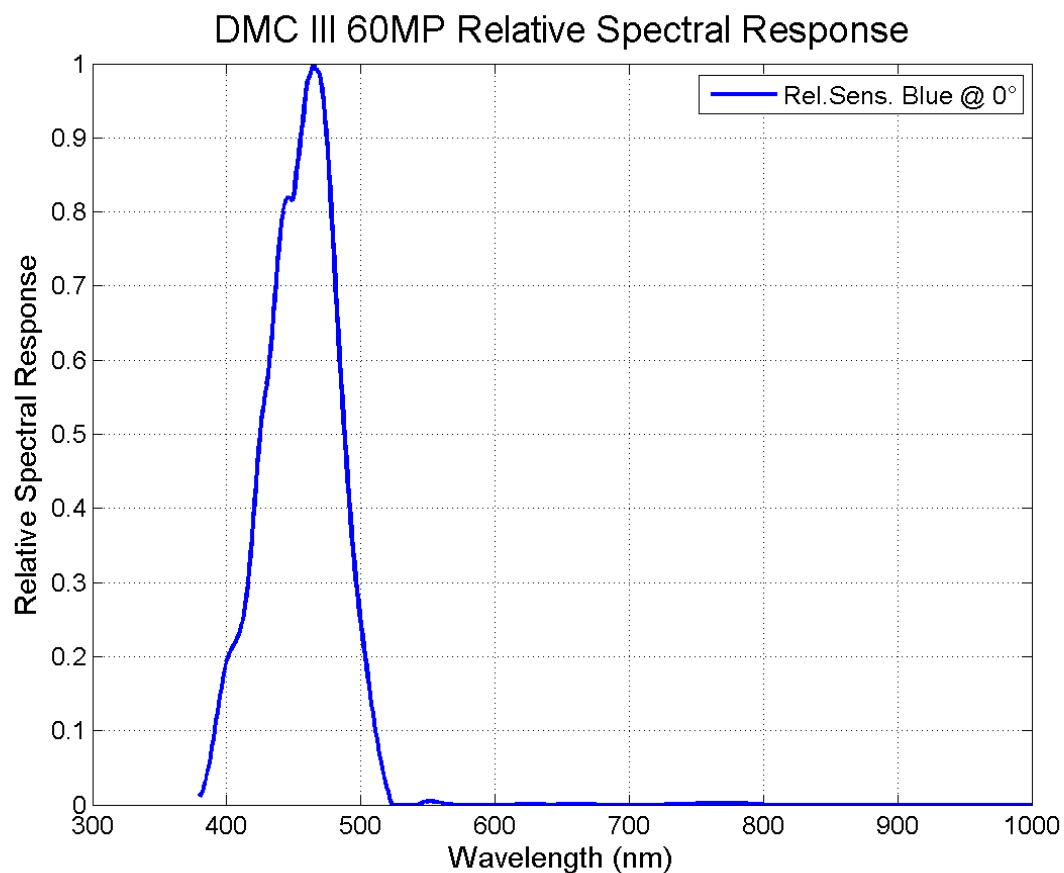
### DMC III MS Blue – MTF F/4.0 ; 45 mm– Temperature Stability



## Radiometric Calibration

### Sensitivity of Blue camera

Spectral Response Curves of the single camera head.



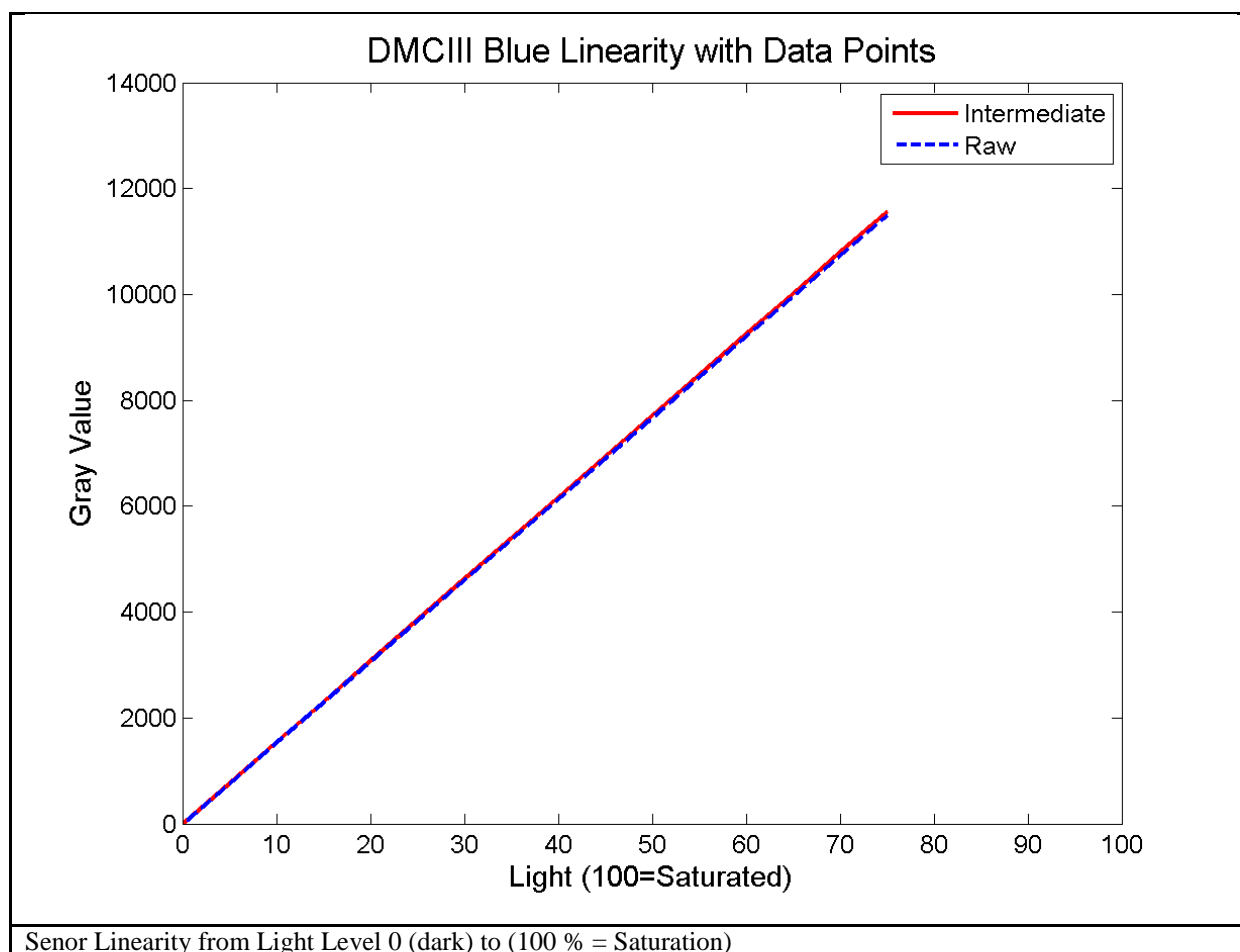
The sensitivity shows the spectral response curve of the single camera head including the optical system (optics, filter) and the sensor response. The DMC III is calibrated with respect to the absolute spectrometer. This allows computing pixel radiance values from pixels digital numbers and is a camera type specific calibration.

## Radiometric Calibration

### Sensor Linearity (Reference)

The sensor linearity is measured in the Lab with calibrated spectrometer. This is a camera type specific calibration.

Below figure shows the linearity of the raw sensor and after flat fielding:



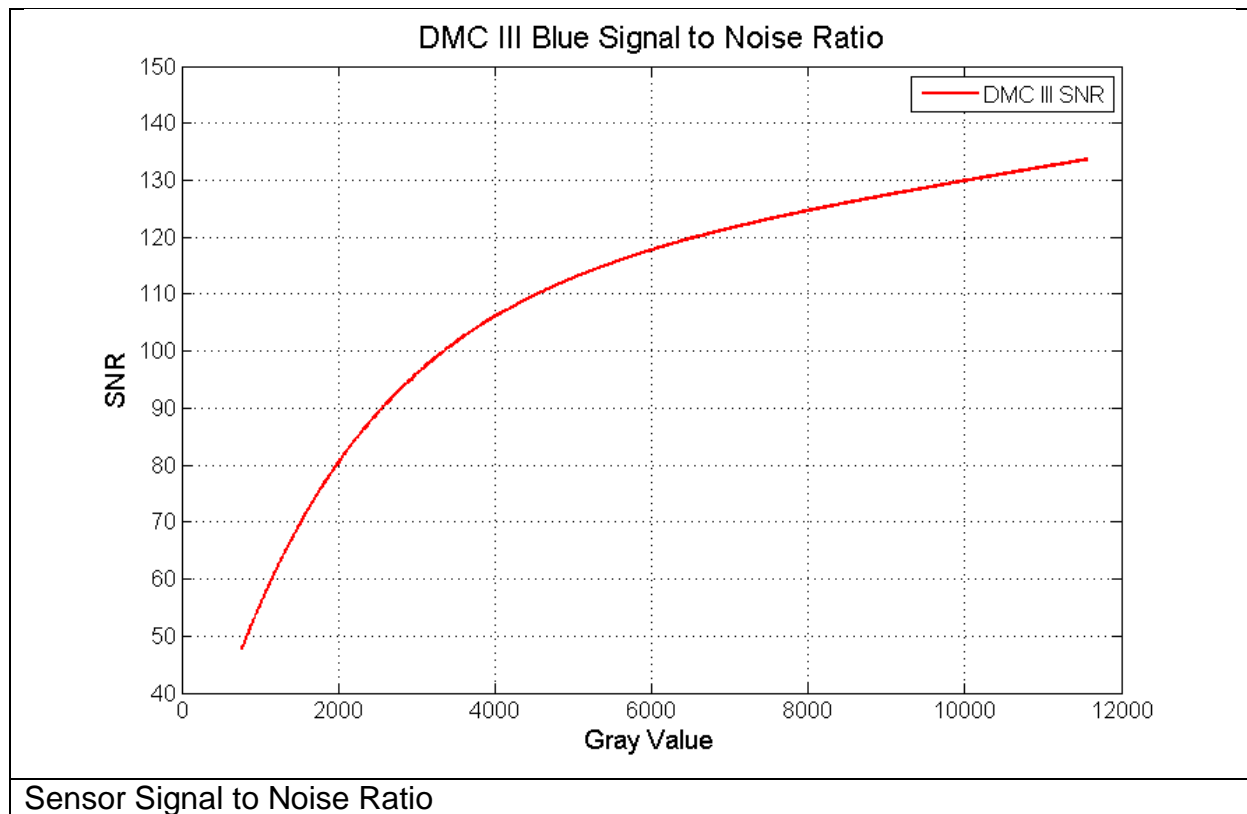
The deviation from the linearity is below 1%.



# Radiometric Calibration

## Sensor Noise (Reference)

Sensor noise shows image noise with respect to the image center measured at an aperture of 5.6 with exposure time of 10msec.

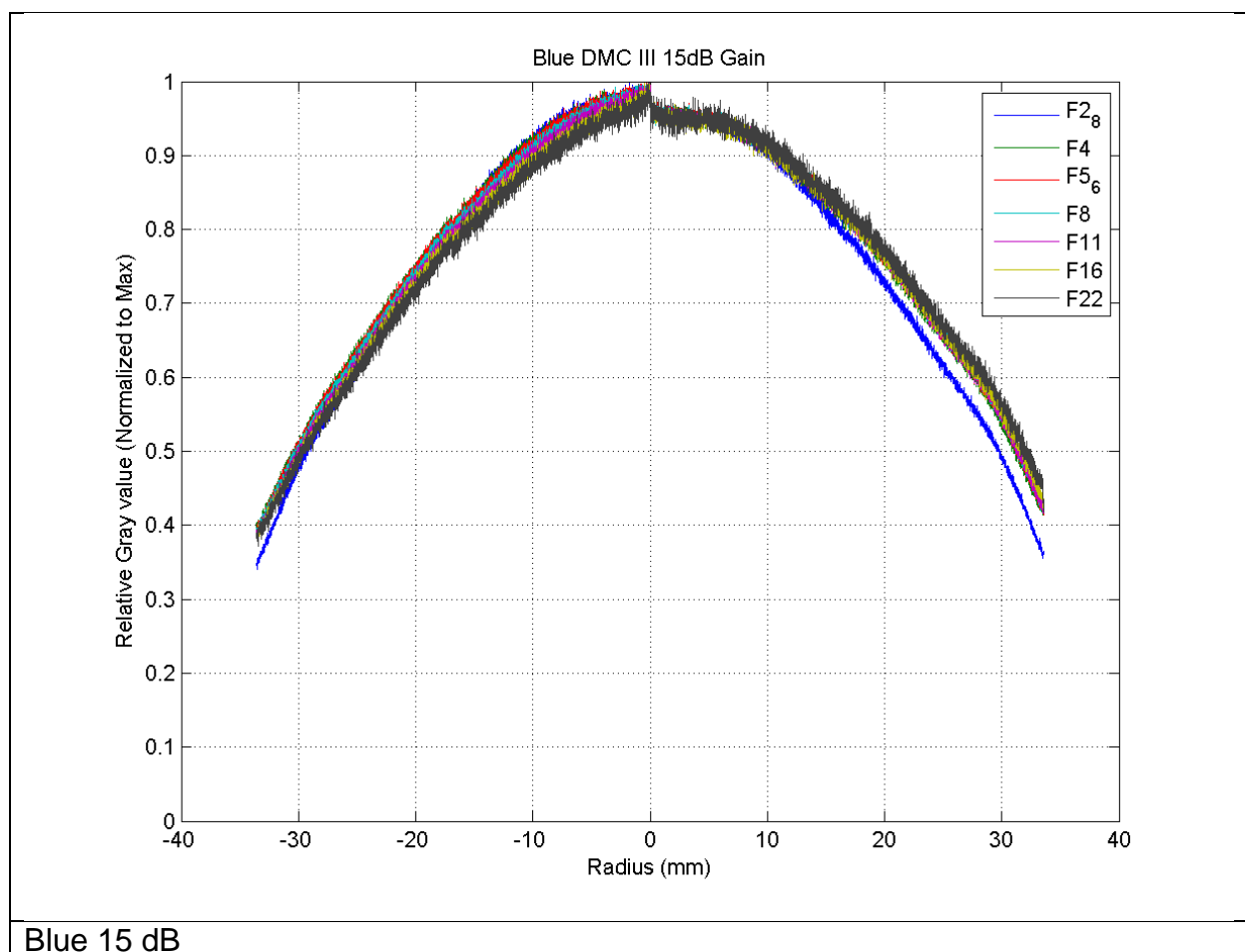


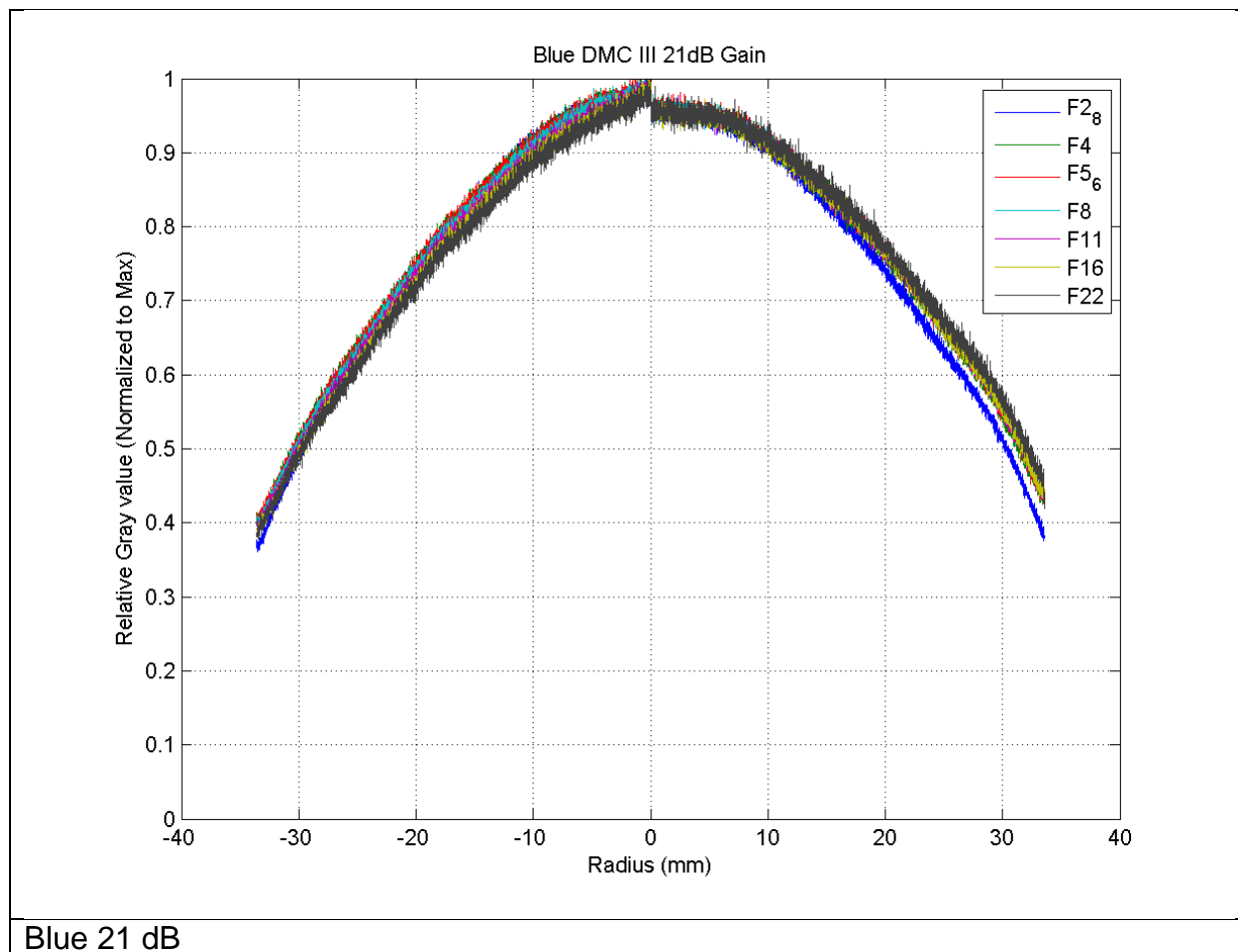
# Radiometric Calibration

## Aperture Correction

### Blue (00128348)

The light fall off to the border due the influence of the optics depends on the used aperture. Therefore this calibration approach has for each aperture (Full F-Stop) its own calibration image. In general the light fall off is a function of the image radius. In this calibration approach instead of function the real measured values in the image is used. The figure below shows the profile from the upper left corner to the lower right corner of each of this calibration images to give a feeling on the amount of correction.





This is a camera type specific calibration.

# Radiometric Calibration

## Defect Pixel

### Blue (00128348)

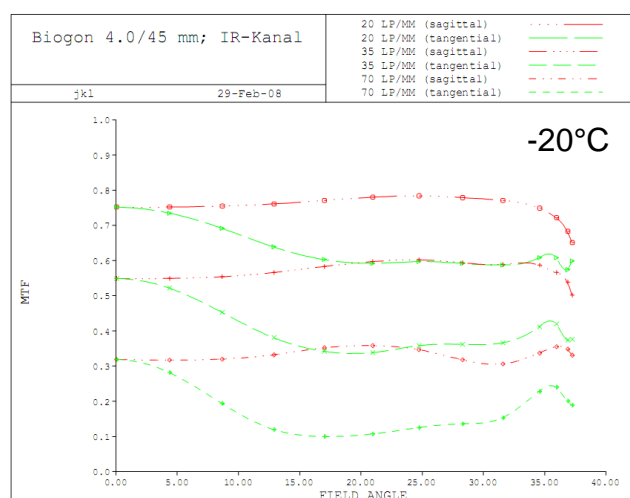
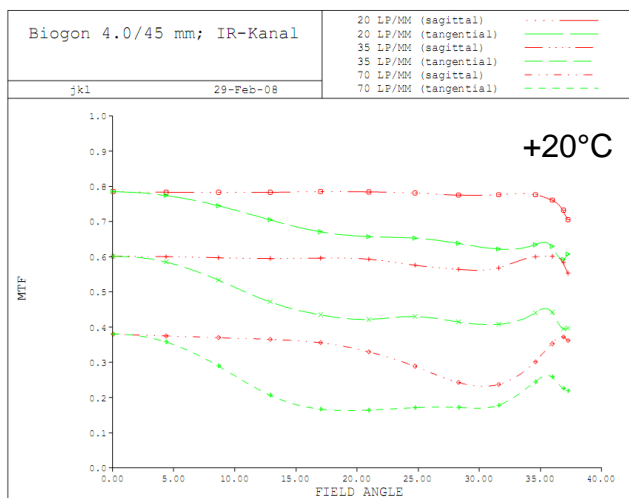
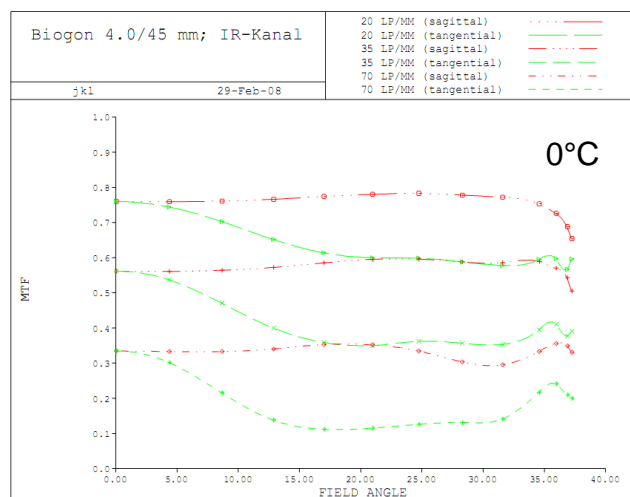
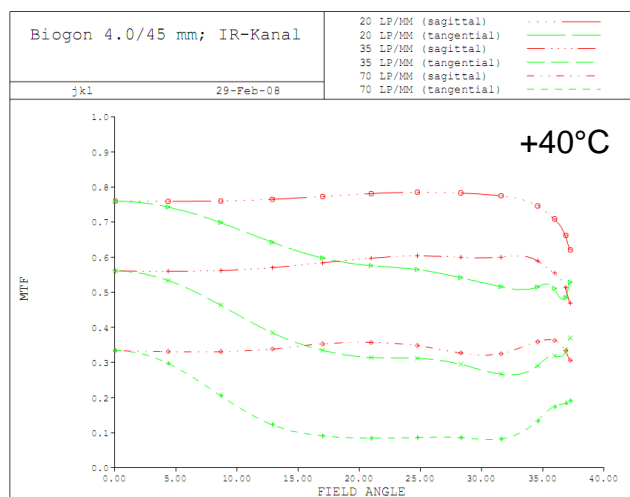
Defect pixels are detected during radiometric calibration and will be corrected during radiometric processing of the images.

The quantity and cumulative percentage and specification of defects are described in Appendix “Defect Pixel Recognition” at page 47.

# Optical System

## Modulation Transfer Function, MTF of IR camera

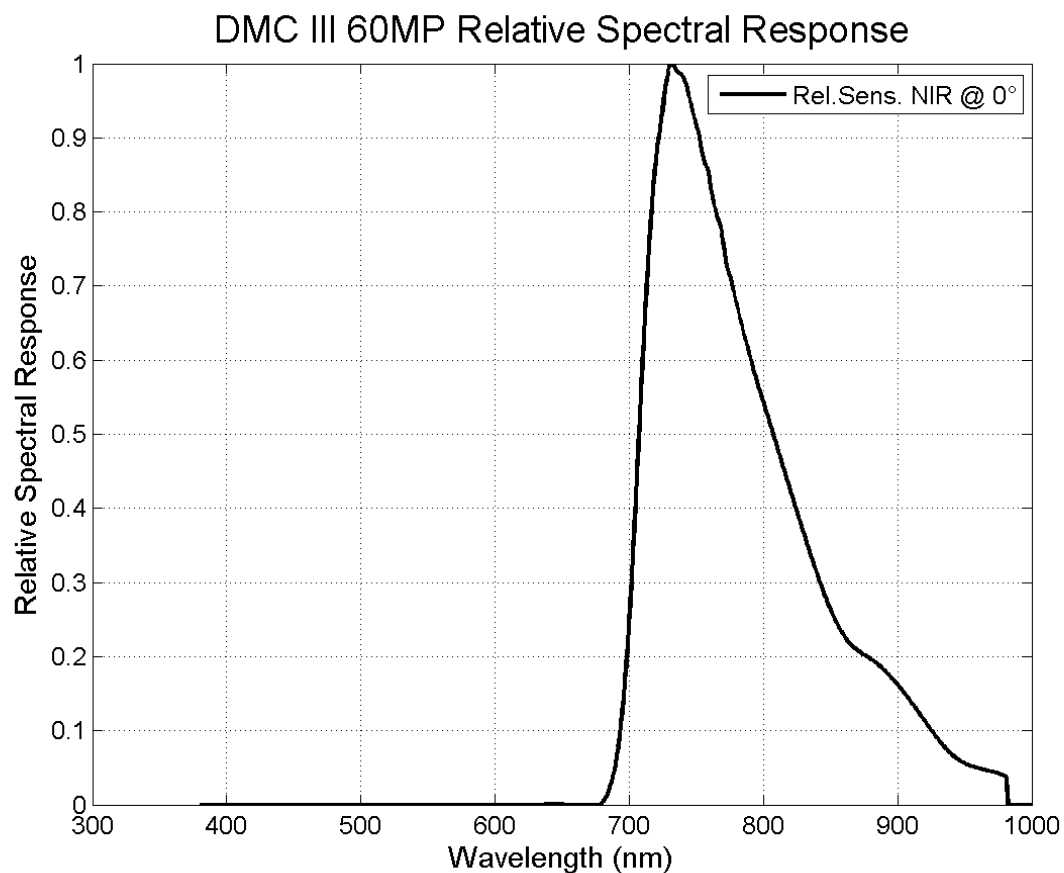
### DMC III MS IR – MTF F/4.0 ; 45 mm– Temperature Stability



## Radiometric Calibration

### Sensitivity of NIR camera

Spectral Response Curves of the single camera head.



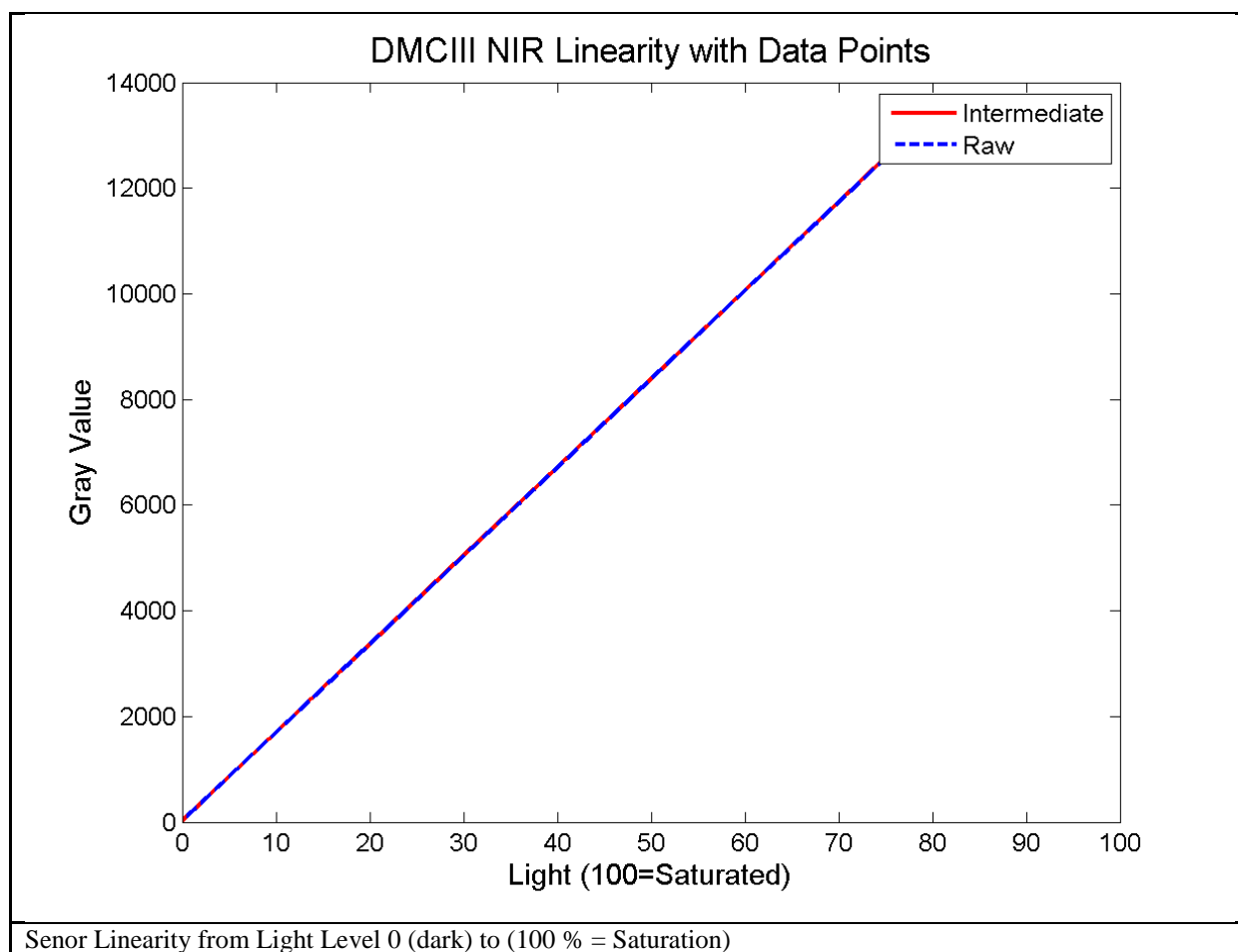
The sensitivity shows the spectral response curve of the single camera head including the optical system (optics, filter) and the sensor response. The DMC III is calibrated with respect to the absolute spectrometer. This allows computing pixel radiance values from pixels digital numbers and is a camera type specific calibration.

## Radiometric Calibration

### Sensor Linearity (Reference)

The sensor linearity is measured in the Lab with calibrated spectrometer. This is a camera type specific calibration.

Below figure shows the linearity of the raw sensor and after flat fielding:

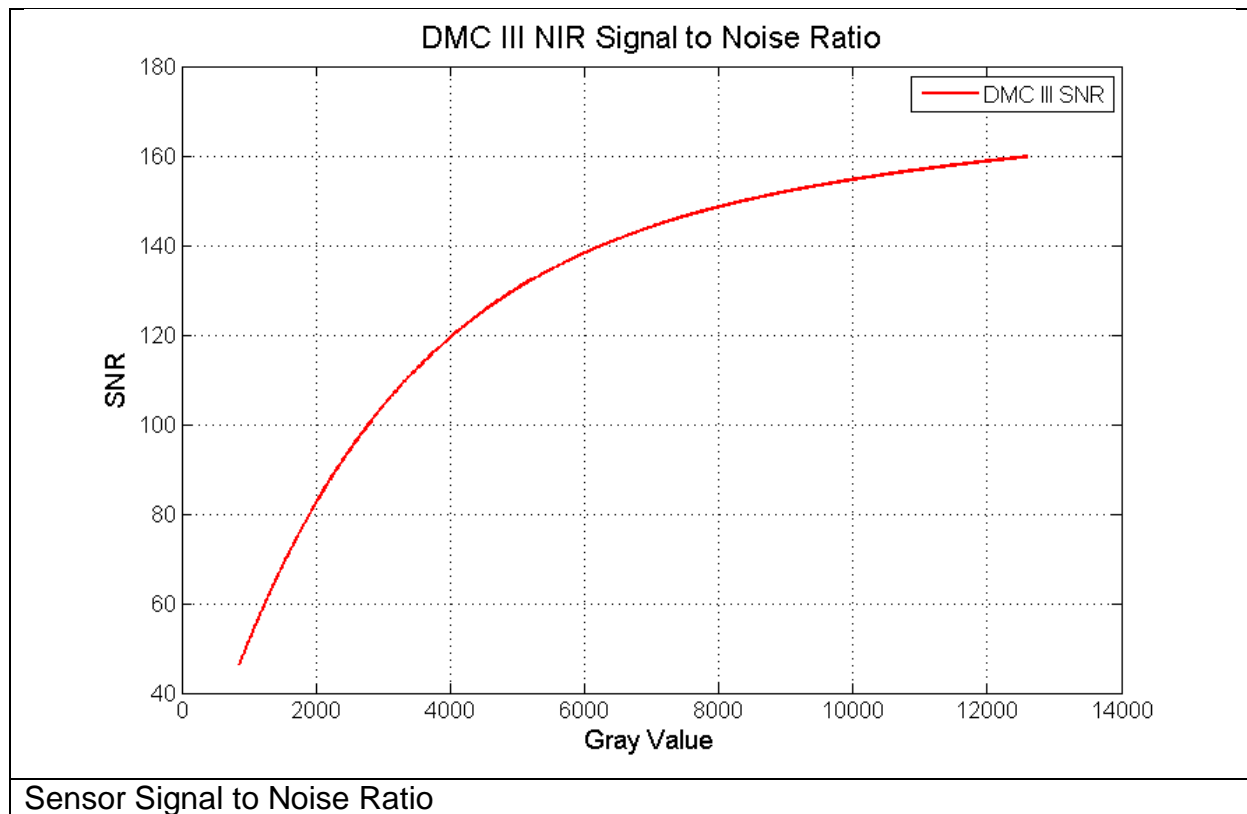


The deviation from the linearity is below 1%.

# Radiometric Calibration

## Sensor Noise (Reference)

Sensor noise shows image noise with respect to the image center measured at an aperture of 5.6 with exposure time of 10msec.



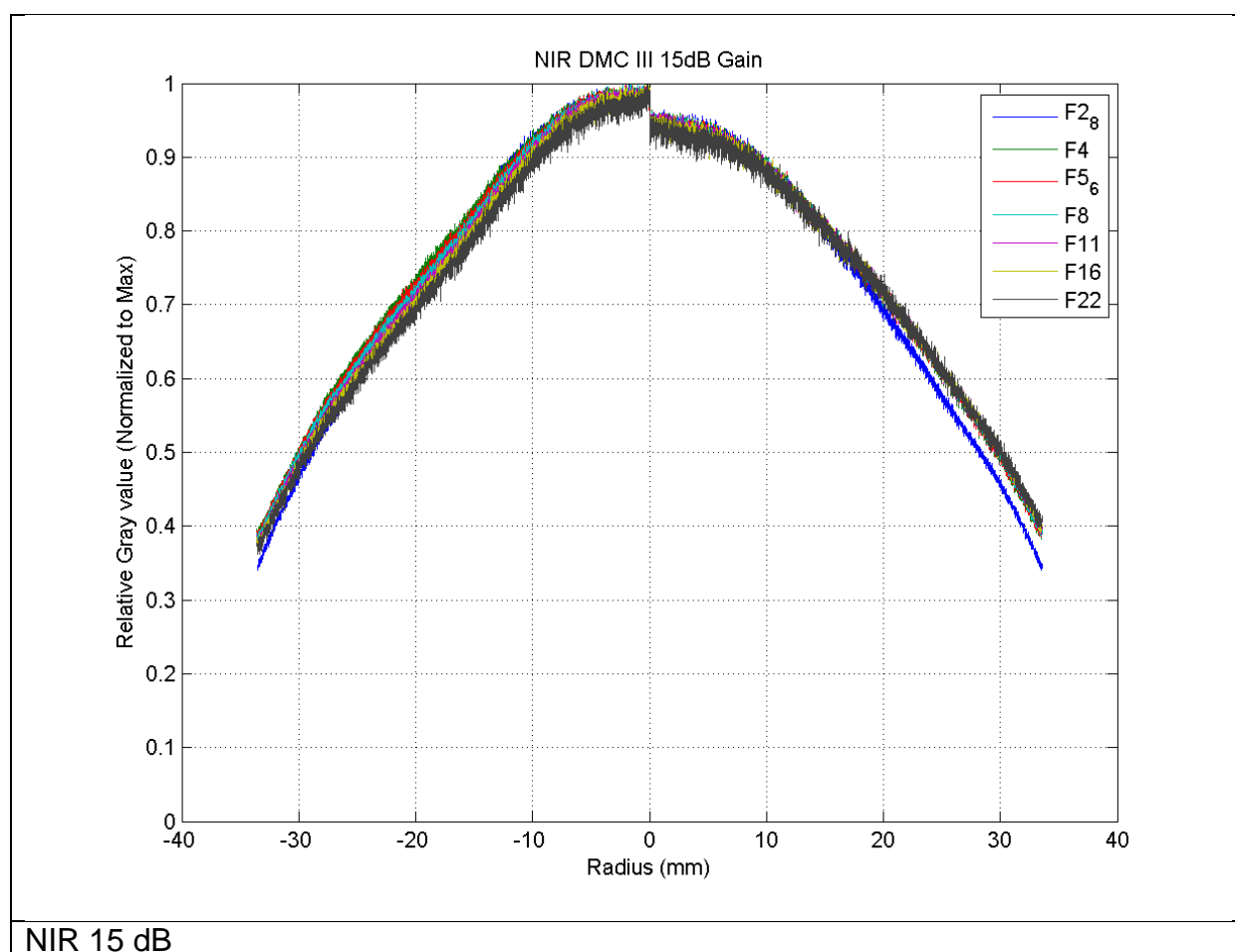


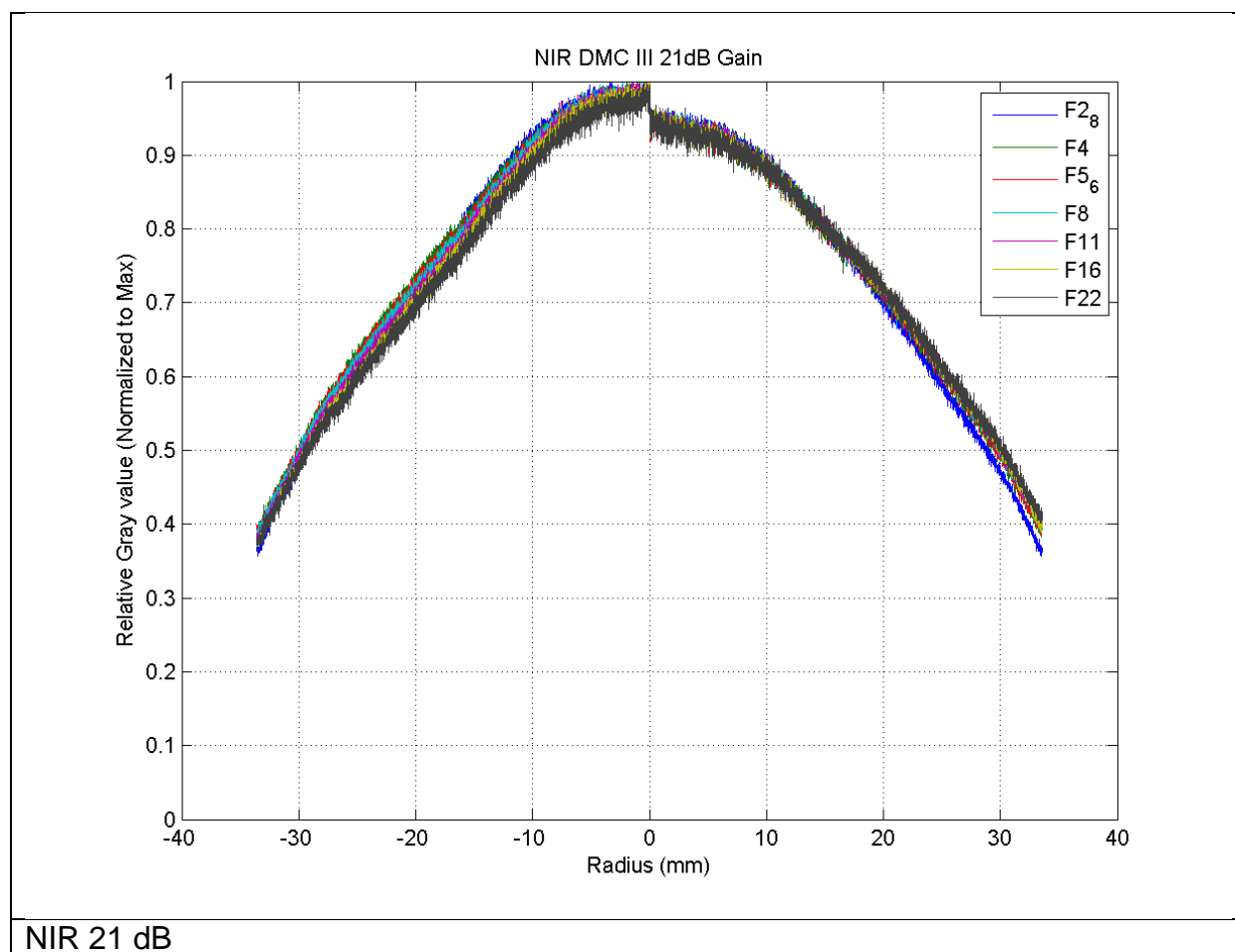
# Radiometric Calibration

## Aperture Correction

### NIR (00128322)

The light fall off to the border due the influence of the optics depends on the used aperture. Therefore this calibration approach has for each aperture (Full F-Stop) its own calibration image. In general the light fall off is a function of the image radius. In this calibration approach instead of function the real measured values in the image is used. The figure below shows the profile from the upper left corner to the lower right corner of each of this calibration images to give a feeling on the amount of correction.





This is a camera type specific calibration.

# Radiometric Calibration

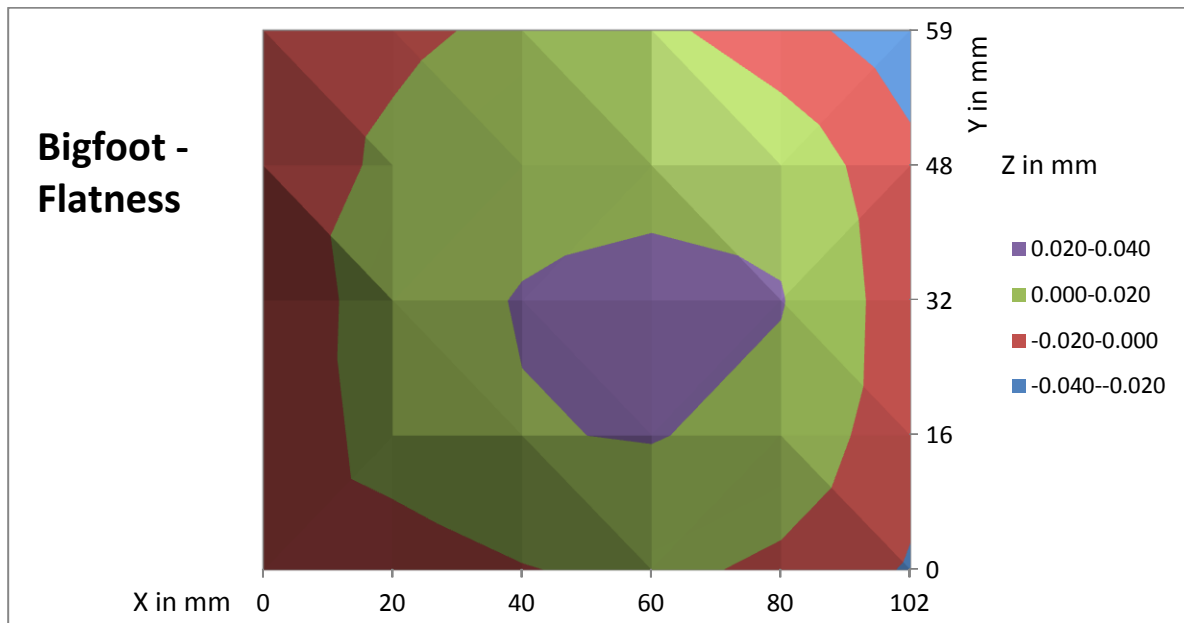
## Defect Pixel

### NIR (00128322)

Defect pixels are detected during radiometric calibration and will be corrected during radiometric processing of the images.

The quantity and cumulative percentage and specification of defects are described in Appendix “Defect Pixel Recognition” at page 47.

## Sensor Geometry



## Radiometric Reference Camera Calibration

The DMC III absolute radiometric calibration uses a reference camera to produce consistent DN and radiance values from all cameras systems. The application of the reference camera values occurs within PPS, when color balancing output is selected. Then, a single set of calibration coefficients, along with the current acquisition F# and exposure time, may be used to convert the color balanced (radiometric corrected) DN values to radiance.

A single, reference camera absolute radiometric calibration coefficient is provided for each camera band. For the multispectral cameras, which have variable gains, the calibration is provided at a single reference gain. These calibration coefficients are applied to image DN values that have been corrected within PPS to match the reference camera. In PPS, the uncorrected, raw DN values are dark image subtracted and flat fielded using the current camera's calibration files. Then the DN values are scaled to the reference camera maximum DN value for the current acquisition F-stop, and if appropriate, scaled to account for differences in gain. Once these corrections have occurred, the DN values are representative of the reference camera. Then, the corrected DN values can be converted to radiance using the following equation:

$$L = C_{ref} \cdot DN' \frac{F\#^2}{\tau}$$

Where:

- C<sub>ref</sub>** -- calibration coefficient (in  $\mu\text{W ms} / (\text{cm}^2 \cdot \text{sr} \cdot \text{nm})$ )
- F#** -- current aperture or f-number
- $\tau$**  -- current exposure time (in ms)
- DN'** -- radiometric corrected DN value output from PPS

## Defect Pixel Recognition

The table below shows the maximal allowed physical defects on the CMOS and CCD Sensors and its definitions.

Description		CMOS/CCD Spec s/n	PAN 00128300 meet spec	GREEN 00128341 meet spec	RED 00128321 meet spec	BLUE 00128348 meet spec	NIR 00128322 meet spec
Pixel	Bright image	Pixel whose signal, at nominal light (illumination at 50% of the linear range), deviates more than $\pm 30\%$ from its neighboring pixels.					
	Dark image	Pixel whose signal, in dark, deviates more than 6mV from its neighboring pixels (about 1% of nominal light).					
	Max Count	PAN $\leq 15000$	yes	---	---	---	---
		MS $\leq 500$	---	yes	yes	yes	yes

Description		CMOS/CCD Spec s/n	PAN 00128300 meet spec	GREEN 00128341 meet spec	RED 00128321 meet spec	BLUE 00128348 meet spec	NIR 00128322 meet spec
Column/Row	Definition	A column which has more than 8 pixel defects in one 1x12 kernel Column defects must be horizontally separated by 5 columns for single line defects and 10 for double line defects					
	Recognition (bright and dark)	Same as defect pixel recognition					
	Max Single Column	PAN $\leq 140$	yes	---	---	---	---
		MS $\leq 20$	---	yes	yes	yes	yes
	Max double Column	PAN $\leq 40$	yes	---	---	---	---
		MS $\leq 6$	---	yes	yes	yes	yes
	Max Single Row	PAN $\leq 140$	yes	---	---	---	---
	Max double Row	PAN $\leq 40$	yes	---	---	---	---

The Post-Processing-Software is correcting following pixel and columns:

PPS Correction	
Pixel	Pixel whose gray value in a 16 x16 kernel differs from the median more than 30%

PPS Correction	
Column	Pixel whose gray value in a 16 x16 kernel differs from the median more than 5% and more than 15 defects in one column

PPS Correction	
Row	Pixel whose gray value in a 16 x16 kernel differs from the median more than 5% and more than 15 defects in one row

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